

TWIN612

Product Specification V1.2

(Observation type & Thermography type)



User Instructions



Precautions for safe use

This content is to ensure that the user uses the product properly to avoid danger or property damage. Before using this product, please read the instructions carefully and properly keep it for future reference.

As shown below, the precautions are divided into two parts, i.e., "warnings" and "cautions":

Warning: Ignoring a warning may result in death or serious injury.

Caution: Ignoring a caution may result in injury or property damage.

| | |
|---|---|
| | |
| Warning Instructions to ensure the users to avoid potential dangers may result in death or serious injury. | Caution Instructions to ensure the users to avoid potential dangers may result in injury or property damage. |



Warnings

- Install and use this product in strict accordance with all relevant national and local electrical safety regulations.
- Use power adapters supplied by legitimate manufacturers, power supply of the module: DC5V/2A.
- Do not connect multiple modules to a power adapter (overload of the adapter may result in excessive heat or fire).
- Power off the module during wiring, disassembly and other operations, do not allow live operation.
- Immediately power off the module off in the event of smoke, stench or noise during its use, and contact the distributor or service center to deal with related matters.
- If the equipment does not work properly, please contact the store where you purchased the equipment or the nearest service center. Do not disassemble or modify the equipment in any way. (We are not liable for any problems arising from unauthorized modification or repair).



Cautions

- Do not drop any object on the equipment or vigorously shake the equipment, and keep the equipment away from magnetic field interference. Avoid installing the equipment to a place where the surface vibrates or is subject to impact. (Ignoring this may damage the equipment).
- Do not use the equipment in environment with high temperature (higher than 70°C) or low temperature (lower than -40°C) or high humidity (higher than 95%).
- Do not expose the module to objects giving out bright light, such as sun, otherwise the module will be damaged.
- Do not place the equipment in a location under direct sunlight or a poorly ventilated location, or near heat source such as heater or heating (ignoring this may cause a fire hazard).
- Do not frequently power on/off the machine, turn it on at least 30 seconds after it is turned off, otherwise the module life will be affected.
- Do not hot swap the 50pin interface, which will cause damage to the module.
- Do not touch the surface coating of the module lens directly with your hand, or scratch the lens with a hard object, which may lead to blurred imaging, affecting image quality.
- Use sufficiently soft dry cloth or other alternatives to wipe the lens surface to clean the module. Do not use alkaline detergent.

Disclaimer

Please ensure that you have read and fully understand the product instructions and the statement before using this product. You should install and use this product in strict accordance with the product instructions. If the user fails to strictly follow the instructions to install and use this product, it may bring great inconvenience to use, and may even cause property damage and personal injury. We assume no legal responsibility for any property damage and personal injury arising from improper installation or improper use of the product.

Service Principle

The series of products enjoy one-month replacement and one-year warranty. The specific service principle shall follow the provisions on the attached warranty card to perform warranty services. For products that have been discontinued, obsolescence or sold at a discount, the execution time shall follow written documents such as the notice of company.

Document Version

| Date | Version | changes | author |
|---------|---------|---|--------|
| 2022/04 | V1.0 | / | WEN |
| 2022/06 | V1.1 | Remove the TBD tags for BT.656 related content | Ding |
| 2022/08 | V1.2 | Add the lens information of module, page7~page9, page84~page85. | Ding |

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1 Product Overview

1.1 Product description

TWIN series core is a high-resolution general-purpose uncooled infrared thermal module, characterized with large area array, high resolution, impact and vibration resistant and good scalability.

TWIN612 is based on the ceramic detector of Global Sensor Technology and has the following features:

- Small size, the whole size is not more than 25.4mm*25.4mm*35mm(without lens)
- The weight is as light as 25.8g
- Fast imaging and less than 6s start-up time
- Power consumption is as low as 0.9W
- Support non-uniformity correction (NUC)
- 3D image noise reduction (3DNR)
- 2D Digital noise reduction (DNS)
- Wide Dynamic Range Compression (DRC)
- EE enhancement
- Strong extension ability, support VPC/USB and other extension components, plug and play, easy to integrate

At the same time, the series movement is equipped with high-performance signal processing circuit and image processing algorithm, which ensures the definition and smoothness of image quality. As a basic thermal imaging module, it provides various industry standard interfaces, which will facilitate secondary development for OEM customers. It offers standard professional thermal imaging solutions for many applications, such as power monitoring, industrial maintenance, security and outdoor sports.

The basic framework of the TWIN module is shown in Figure 1-1.

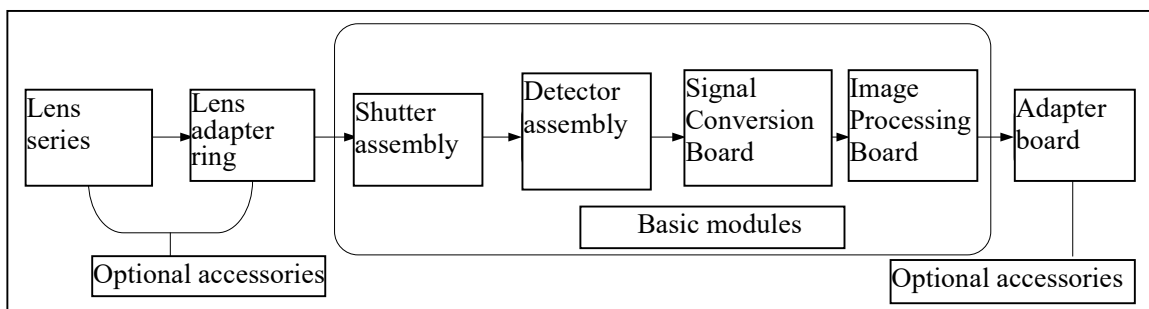


Figure 1-1 Basic framework of TWIN module

The basic core module is the basic unit of the core, which mainly completes the basic imaging functions of the infrared thermal module, including the shutter assembly, the detector assembly, the image processing assembly and the power supply unit. The shutter assembly uses an electromagnetic valve shutter, which has the advantages of good uniformity and short response time. The detector assembly includes infrared detector, PCB and inter-board connector. The signal conversion board is used to realize basic signal processing circuits and time-series transmission channels. The image processing board is mainly used to complete the image processing, analog video and digital video output, as well as power supply of the whole system.

1.2 Product configuration

1.2.1 Technical specification — TWIN612(Observation type)

Detector: uncooled vanadium oxide, 640x512

- Pixel pitch: 12um
- Spectral: 8~14um
- NETD: $\leq 40\text{mk@F1.0@25}^{\circ}\text{C}$

Output: supports analog video and digital video

Output frame frequency: 25hz / 30hz configurable, default 25hz

Analog video: CVBS, 75 Ω characteristic impedance

Support PAL system and NTSC system, switchable

Digital video:

Support 8bit/16bit parallel CMOS, default 8bit;

Support USB2.0 digital video;

Support BT.656(8bit, progressive) ;

Control communication: RS232-TTL/USB(Select-able)

- Boot time: $\leq 6\text{S}$, Boot screen supports customization

Physical properties

- lens:13mm/25mm/35mm/50mm/70mm
- Dimension: 25.4mm*25.4mm*35.0mm(without lens)
- Assembly interface

13mm/25mm lens: M1.6x 3.5, 2pc / side, 3 sides in total

35mm lens: M2x 3.5, 2pc / side, 3 sides in total

50mm/70mm lens: (1) mounting hole: M2x 3.5, 4pc / side, 1 sides in total

(2) locating hole: $\Phi 1.5, 4\text{pc / side, 1 sides in total}$

Electrical properties

- Power supply: DC 4-5.5V, typical power consumption $\leq 0.9\text{W @ } 5\text{V @ } 23 \pm 3^{\circ}\text{C}$
- Expansion board: USB2.0 board/USB3.0 board/VPC board,plug and play

Environmental properties

- Working temperature: -40°C to $+70^{\circ}\text{C}$

- Storage temperature: -45°C to +85°C
- Humidity: No condensation at 5% - 95% RH
- Impact and vibration resistance:
Vibration: 5.35grms,3 axis
Impact: half sine wave,40g/11ms,3-axis,6-direction
- ROHS Certification

1.2.2 Technical specification — TWIN612R(Thermography type)

Detector: uncooled vanadium oxide, 640x512

- Pixel pitch: 12um
- Spectral: 8~14um
- NETD: ≤ 40mk@F1.0@25°C

Output: supports analog video and digital video

Output frame frequency: 25hz / 30hz configurable, default 30hz

Analog video: CVBS, 75Ω characteristic impedance

Support PAL system and NTSC system, switchable

Digital video:

Support 8bit/16bit parallel CMOS, default 8bit;

Support usb2.0 digital video;

Support BT.656(8bit, progressive);

Control communication: RS232-TTL/USB(option)

- Boot time: ≤6S, Boot screen supports customization
- Support image enhancement and pseudo-color
- Support SDK for secondary development and function extension

Physical properties

- lens: 13mm
- Dimension: 25.4mm*25.4mm*35mm (without lens)
- Assembly interface: M1.6x3.5, 2pc / side, 3 sides in total

Electrical properties

- Power supply: DC 4-5.5V, typical power consumption ≤ 0.9W @ 5V @23 ± 3°C
- Expansion board: USB2.0 board, plug and play

Environmental properties

- Working temperature: -40°C to +70°C
- Storage temperature: -45°C to +85°C
- Humidity :No condensation at 5% - 95% RH
- Impact and vibration resistance:
Vibration: 5.35grms,3 axis
Impact: half sine wave,40g/11ms,3-axis,6-direction
- ROHS2.0/REACH

Thermography:

- Temperature measuring range: -10°C ~ +50°C.
- Temperature accuracy: $\pm 2^{\circ}\text{C}$ 或 $\pm 2\%$ (maximum value)@ $23^{\circ}\text{C} \pm 3^{\circ}\text{C}$, Temperature measuring distance: 5m.
- Temperature range: -20°C~+150°C, 0~550°C, specific requirements can be customized.
- Area temperature measurement: supports any area temperature measurement, output area maximum, minimum and average value.
- Point temperature measurement: supports any point temperature measurement.
- Provide Windows/Linux version SDK to realize video stream analysis and grayscale to temperature conversion.
- Support pseudo color (≥ 11 kinds), specific requirements can be customized.

1.2.3 Optical configuration

The optical configuration of the TWIN module is shown in Table 1-1.

Table 1-1 Optical configuration

| Focal length | Coating | Resolution | f/# | FOV (H×V, $\pm 5\%$) | Size (Module+Lens) | Weight (Module+Lens) |
|----------------|---------|------------------|-----|-----------------------|--------------------|----------------------|
| 13mm(Athermal) | DLC | 640×512@ 12um | 1.0 | 32.9°x26.6° | 25.4mm*25.4mm*48mm | 48g |
| 25mm(Athermal) | DLC | 640×512@ 12um | 1.0 | 17.46°x14° | Φ35.4mm*52.75mm | 75.5g |
| 35mm(Athermal) | DLC | 640×512@ 12um | 1.0 | 12.52°x10° | Φ48.4mm*64.3mm | 131g |
| 50mm(Athermal) | DLC | 640×512@ 12um | 1.0 | 8.78°x7.03° | Φ62mm*77.1mm | 188g |
| 70mm(Athermal) | DLC | 640×512@ 12um | 1.0 | 6.28°x5.03° | Φ84mm*104.5mm | 440g |

Note:

Lenses series of TWIN612 support front lens IP67,DLC stand for Hard-carbon film.

1.3 Description of PC control software

Infrared Camera Controller enables online control of the TWIN series.

The PC control software can be used in windows 7/8/10/XP and other operating systems.

Support Chinese/English language.

The typical baud rate is 115200.

1.4 Unpacking

The standard configuration chassis contains a module, a product certificate and accessories.

The module shall be unpacked and used in environment with good electrostatic protection as it contains electrostatic sensitive electronic components. The module shall be put in an antistatic bag to avoid electrostatic damage.

The packing box shall be filled with foam material to prevent damage to the module during transport.

2 Electrical interface instructions

2.1 Input power requirements

The steady-state power consumption of TWIN612 module $\leq 0.9W@5V, 23\pm 3^{\circ}C$

When compensating the shutter, the transient power consumption $\leq 2W@1s$;

Insufficient power supply may cause abnormality in start-up and operation.

When using expansion board, the power supply voltage range of the module is: DC:4V-5.5V. This voltage refers to the voltage supplied to the circuit board. In practical application, please consider the influence of line loss and reserve sufficient margin.

2.2 Hardware Interface

The external interface of bare TWIN module is 50PIN interface which includes functions of power input/ output, digital/analog video output, RS232-TTL serial port and independent IO etc.

The external interface model of module is:DF40C-50DP-0.4V (51), (HRS, male connector). The recommended external interface model is: DF40HC (3.5)-50DS-0.4V (51), (HRS, female connector).

The position of HRS 50-PIN interface on the circuit board and the pin sequence are shown in Fig. 2-1, XS1. The dimension unit in Fig. 2-1 is mm; relative to the upper left positioning hole center, the coordinate of the first pin center for 50Pin base is (6.41, 1.62).

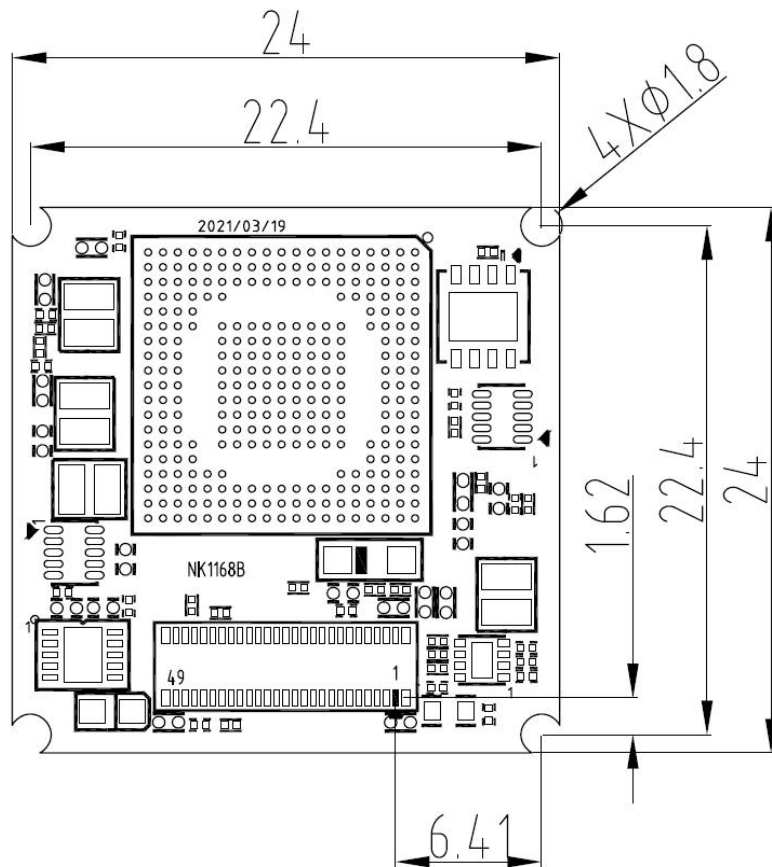


Fig. 2-1 The coordinate diagram and the entity of HRS 50-PIN interface

The definition of HRS 50-PIN external interface is shown in Table 2-1.

Table 2-1 The definition of 50-PIN interface

| S/N | Signal definition | Signal direction | Level | Description |
|-----|----------------------|------------------|-------------|---|
| 1 | UART0_TXD/ USB_DM | O/IO | H 3.3V/L 0V | Send UART0 (core port, the same below)/ USB2.0_DM |

| | | | | |
|----|----------------------|----------|-------------|-------------------------------|
| 2 | UART0_RXD/ USB_DP | I/O | H 3.3V/L 0V | Receive UART0/ USB2.0_DP |
| 3 | Reserved | O | / | NC |
| 4 | Reserved | O | / | NC |
| 5 | I2C_SCL | IO | H 1.8V/L 0V | Clk of I2C BUS |
| 6 | I2C_SDA | IO | H 1.8V/L 0V | Sda of I2C BUS |
| 7 | DGND | GND | 0V | Power ground |
| 8 | DGND | GND | 0V | Power ground |
| 9 | DATA_VALID | O | H 1.8V/L 0V | |
| 10 | DGND | GND | 0V | NC |
| 11 | LVDS_CLK_P | O | H 1.8V/L 0V | NC |
| 12 | LVDS_CLK_N | O | H 1.8V/L 0V | NC |
| 13 | LVDS_DATA0_P | O | H 1.8V/L 0V | NC |
| 14 | LVDS_DATA0_N | O | H 1.8V/L 0V | NC |
| 15 | LVDS_DATA1_P | O | H 1.8V/L 0V | NC |
| 16 | LVDS_DATA1_N | O | H 1.8V/L 0V | NC |
| 17 | DGND | GND | 0V | Power ground |
| 18 | DGND | GND | 0V | Power ground |
| 19 | DIGITAL_HS | O | H 1.8V/L 0V | Digital video signal |
| 20 | DIGITAL_VS | O | H 1.8V/L 0V | Digital video signal |
| 21 | DATA_OUT15 | O | H 1.8V/L 0V | Digital video signal |
| 22 | DATA_OUT14 | O | H 1.8V/L 0V | Digital video signal |
| 23 | DATA_OUT13 | O | H 1.8V/L 0V | Digital video signal |
| 24 | DATA_OUT12 | O | H 1.8V/L 0V | Digital video signal |
| 25 | DATA_OUT11 | O | H 1.8V/L 0V | Digital video signal |
| 26 | DATA_OUT10 | O | H 1.8V/L 0V | Digital video signal |
| 27 | DATA_OUT9 | O | H 1.8V/L 0V | Digital video signal |
| 28 | DATA_OUT8 | O | H 1.8V/L 0V | Digital video signal |
| 29 | DATA_OUT7 | O | H 1.8V/L 0V | Digital video signal |
| 30 | DATA_OUT6 | O | H 1.8V/L 0V | Digital video signal |
| 31 | DATA_OUT5 | O | H 1.8V/L 0V | Digital video signal |
| 32 | DATA_OUT4 | O | H 1.8V/L 0V | Digital video signal |
| 33 | DATA_OUT3 | O | H 1.8V/L 0V | Digital video signal |
| 34 | DATA_OUT2 | O | H 1.8V/L 0V | Digital video signal |
| 35 | DATA_OUT1 | O | H 1.8V/L 0V | Digital video signal |
| 36 | DATA_OUT0 | O | H 1.8V/L 0V | Digital video signal |
| 37 | DGND | GND | 0V | Power ground |
| 38 | DGND | GND | 0V | Power ground |
| 39 | DATA_OUT_CLK | O | 0V | Clock signal |
| 40 | EXT_SYNC | I/O | 0V | External synchronizing signal |
| 41 | DGND | GND | 0V | Power ground |
| 42 | DGND | GND | 0V | Power ground |
| 43 | VIDEO_OUT | O | 0-1V | Analog video signal output |
| 44 | VIDEO_AGND | GND | 0V | Analog video ground |
| 45 | DGND | GND | 0V | Power ground |
| 46 | POWER_IN | POWER-IN | 4-5.5V | Power input |
| 47 | DGND | GND | 0V | Power ground |
| 48 | POWER_IN | POWER-IN | 4-5.5V | Power input |
| 49 | DGND | GND | 0V | Power ground |
| 50 | 1.8V | O | 1.8V | 1.8V Power Output |

Note: The signal direction “O” stands for the output, “I” stands for the input and “NC” stands for suspend.

The digital signal Y8/Y16/ BT.656 hardware physical interface is compatible, and the digital signal output type can be switched by ICC control software.

When customers use external synchronous signal, the pin must connect 10 k Ω resistance and drop down to GND.

The multiplex digital signal hardware interface is shown in Table 2-2

Table 2-2 The definition of digital port

| Signal definition | Interface S/N | Output type of digital port | | |
|-------------------|---------------|-----------------------------|---------------------|-----------|
| | | Parallel port 8bit | Parallel port 16bit | BT.656 |
| DATA_OUT_CLK | 39 | Y8_CLK | Y16_CLK | BT656_CLK |
| EXT_SYNC | 40 | EXT_SYNC | EXT_SYNC | / |
| DATA_OUT0 | 36 | Y8_D0 | Y16_D0 | BT656_D0 |
| DATA_OUT1 | 35 | Y8_D1 | Y16_D1 | BT656_D1 |
| DATA_OUT2 | 34 | Y8_D2 | Y16_D2 | BT656_D2 |
| DATA_OUT3 | 33 | Y8_D3 | Y16_D3 | BT656_D3 |
| DATA_OUT4 | 32 | Y8_D4 | Y16_D4 | BT656_D4 |
| DATA_OUT5 | 31 | Y8_D5 | Y16_D5 | BT656_D5 |
| DATA_OUT6 | 30 | Y8_D6 | Y16_D6 | BT656_D6 |
| DATA_OUT7 | 29 | Y8_D7 | Y16_D7 | BT656_D7 |
| DATA_OUT8 | 28 | / | Y16_D8 | / |
| DATA_OUT9 | 27 | / | Y16_D9 | / |
| DATA_OUT10 | 26 | / | Y16_D10 | / |
| DATA_OUT11 | 25 | / | Y16_D11 | / |
| DATA_OUT12 | 24 | / | Y16_D12 | / |
| DATA_OUT13 | 23 | / | Y16_D13 | / |
| DATA_OUT14 | 22 | / | Y16_D14 | / |
| DATA_OUT15 | 21 | / | Y16_D15 | / |
| DIGITAL_VS | 20 | Y8_FIELD_VALID | Y16_FIELD_VALID | / |
| DIGITAL_HS | 19 | Y8_LINE_VALID | Y16_LINE_VALID | / |

Notes:

Y16 data are parallel 16bit data, Y16_D0 stands for low order, and Y16_D15 stands for high order.

Y8 data are parallel 8bit data, Y8_D0 stands for low order, and Y8_D7 stands for high order.

YUV format , 16bit parallel data: D15~D8 is Y signal, D7~D0 is UV data;

EXT_SYNC: Only for external synchronization requirements, not necessary digital port signal, support external synchronization input and external synchronization output mode, when do not use the external synchronization interface, be sure to turn off the external synchronization function.

2.3 Details of digital video

Data format: output by cb, y, cr, y or y, cb, y, cr;

Support line by line mode, do not support separate line mode;

You can configure the clock according on the resolution size, or customize the blanking rows and head numbers;

Resolution

Yuv or raw: The maximum support resolution is 640 x 515, the effective resolution is 640 x 515, there are 3 rows of parameter line data, and the rest of the data is avoiding synchronous code data 0xfe. The resolution can be assigned to 640 x 512 or 640 x 515 in applications.

Yuv + raw: The maximum support resolution is 1280 x 516, where the effective resolution is 1280 x 512, with another 3 lines of parameter line data and avoidance synchronization code data. It can be configured as 1280 x 512 or 1280 x 515 applications.

Only transmission by frame is supported, and two transfers are not supported for the same frame data.

The movement supports a variety of digital video formats for output. The output video clock is related to the standard, frame frequency and cmos interface bit width, as shown in Table 2-3.

Table 2-3 Overview of digital video clock (Unit: MHz)

| Data source | resolution | 640*512 | |
|-------------------|--|-----------|------|
| | Frame rate | 25Hz/30Hz | |
| | Bit width | 16bit | 8bit |
| Y16 | 10.875 | 21.75 | |
| Y16+para. | 10.875 | 21.75 | |
| YUV422 | 10.875 | 21.75 | |
| YUV422+para. | 10.875 | 21.75 | |
| YUV422+Y16 | 21.75 | 43.5 | |
| YUV422+Y16+ para. | 21.75 | 43.5 | |
| BT656 (TBD) | / | 21.75 | |
| NOTE | 1. BT656 25 valid resolution is 640*512. | | |

The data format is as follows:

Y16

- CMOS16 : Y16[15:0], Y16[15:0], etc
- CMOS8(MSB) : Y16[15:8],Y16[7:0], Y16[15:8],Y16[7:0],etc
- CMOS8(LSB) : Y16[7:0],Y16[15:8], Y16[7:0],Y16[15:8],etc

YUV422

- CMOS16 : YCb[15:0],YCr[15:0], YCb[15:0],YCr[15:0],etc
- CMOS8(MSB) : Y[7:0],Cb[7:0],Y[7:0],Cr[7:0],Y[7:0],Cb[7:0],Y[7:0],Cr [7:0],etc
- CMOS8(LSB) : Cb[7:0],Y[7:0], Cr[7:0],Y[7:0], Cb[7:0],Y[7:0], Cr[7:0],Y[7:0], etc

Note :

1. CMOSx use x physical channel for data transmission;

2. Parameter line format :

- CMOS16 : Head1[15:0], Head2[15:0], Para1[15:0] , Para2[15:0]...Para40[15:0] , End1[15:0] , End2[15:0] ;
- CMOS8(MSB) : Head1[15:8] ,Head1 [7:0], Head2[15:8] ,Head2 [7:0],Para1[15:8] ,Para1[7:0] , Para2[15:8] ,Para2[7:0] ...Para40[15:8] ,Para40[7:0] End1[15:8],End1[7:0] ,End2[15:8],End2[7:0] ;
- CMOS8(LSB) : Head1[7:0], Head1 [15:8], Head2[7:0], Head2 [15:8], Para1[7:0], Para1[15:8] , Para2[7:0] ,Para2[15:8] ...Para40[7:0] ,Para40[15:8] End1[7:0],End1[15:8] ,End2[7:0],End2[15:8] ;

2.3.1 8bits parallel data (CMOS8)

2.3.1.1 CMOS8 without parameter line

The timing of 8bits parallel digital video (without parameter line)are shown in Table 2-4, Table 2-5.

Table 2-4: 8bits video timing (without parameter line)(30HZ)

| Video format | 30Hz (Y16/YUV422) | | | 30Hz (Y16+YUV422) | | |
|--------------|----------------------|---------------|----------|----------------------|---------------|----------|
| | Description | Typical value | Unit | Remarks | Typical value | Unit |
| Resolution | 640*512 | | | 1280*512 | | |
| NW | 640 | | | 1280 | | |
| NH | 512 | | | 512 | | |
| DIGITAL_CLK | 21.75 | MHz | | 43.5 | MHz | |
| TLine | 62.20 | us | 1352CLK | 62.20 | us | 2704 CLK |
| TLine_Valid | 58.85 | us | 1280 CLK | 58.85 | us | 2560 CLK |
| TLine_Blank | 3.34 | us | 72 CLK | 3.34 | us | 144 CLK |
| TPixel | 0.046.. | us | 1 CLK | 0.023.. | us | 1 CLK |
| TStart | / | us | / | / | us | / |
| TFrame | 33.33 | ms | 536 Line | 33.33 | ms | 536 Line |
| TField_Valid | 31.84 | ms | 512 Line | 31.84 | ms | 512 Line |
| TField_Blank | 1.49 | ms | 24Line | 1.49 | ms | 24 Line |

Table 2-5: 8bits video timing (without parameter line)(25HZ)

| Video format | 25Hz (Y16/YUV422) | | | 25Hz (Y16+YUV422) | | |
|--------------|----------------------|---------------|----------|----------------------|---------------|----------|
| | Description | Typical value | Unit | Remarks | Typical value | Unit |
| Resolution | 640*512 | | | 1280*512 | | |
| NW | 640 | | | 1280 | | |
| NH | 512 | | | 512 | | |
| DIGITAL_CLK | 21.75 | MHz | | 43.5 | MHz | |
| TLine | 62.20 | us | 1352CLK | 62.20 | us | 2704CLK |
| TLine_Valid | 58.85. | us | 1280 CLK | 58.85 | us | 2560 CLK |
| TLine_Blank | 3.34 | us | 72 CLK | 16.18 | us | 144 CLK |
| TPixel | 0.046.. | us | 1 CLK | 0.023.. | us | 1 CLK |
| TStart | / | us | / | / | us | / |
| TFrame | 40 | ms | 643 Line | 40 | ms | 643 Line |
| TField_Valid | 31.84 | ms | 512 Line | 31.84 | ms | 512 Line |
| TField_Blank | 8.16 | ms | 131 Line | 8.16 | ms | 131 Line |

The frame timing without parameter line for Y16/YUV422 is shown in Figure 2-2

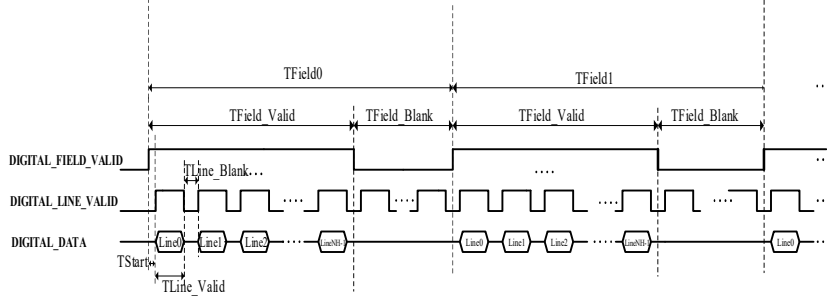


Figure 2-2 Y16/YUV422(without parameter line) timing diagram

The timing of 8bits parallel data for Y16 is shown in Figure 2-3.

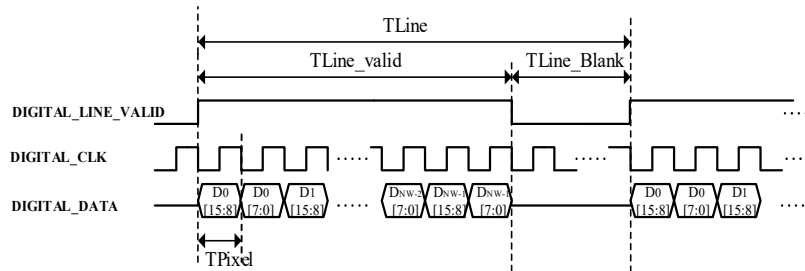


Figure 2-3a Y16 (MSB) timing diagram

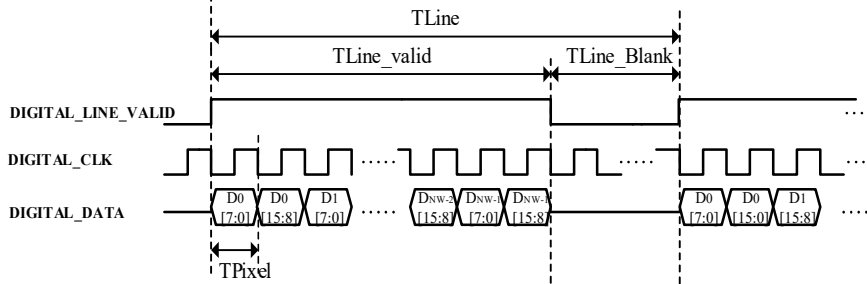


Figure 2-3b Y16 (LSB) timing diagram

The timing of 8bits parallel data for YUV422 is shown in Figure 2-4.

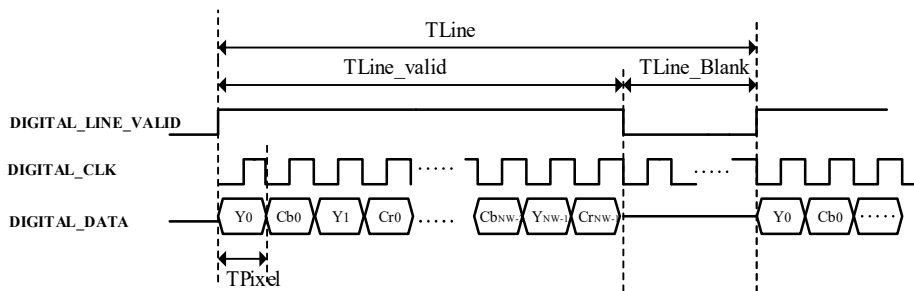


Figure 2-4a YUV422 (MSB) timing diagram

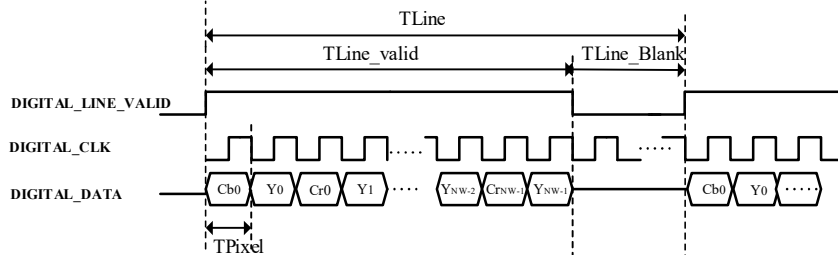


Figure 2-4b YUV422 (LSB) timing diagram

The row of the data source is YUV422 Y16 and the data timing diagram is shown in Figure 2-5.

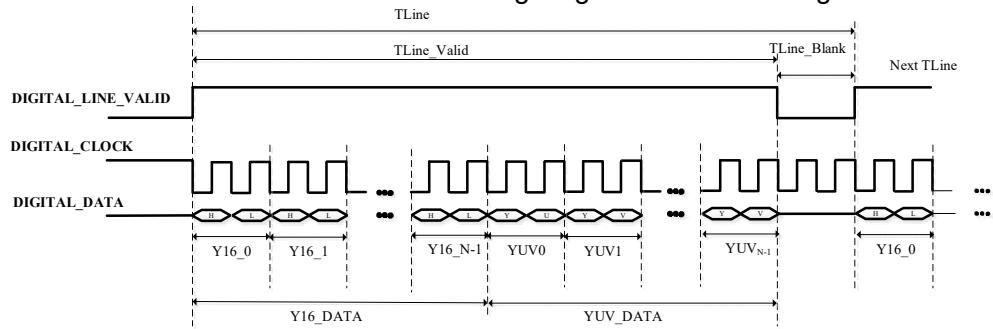


Figure 2-5a YUV422+Y16 (MSB) row and data sequence diagram

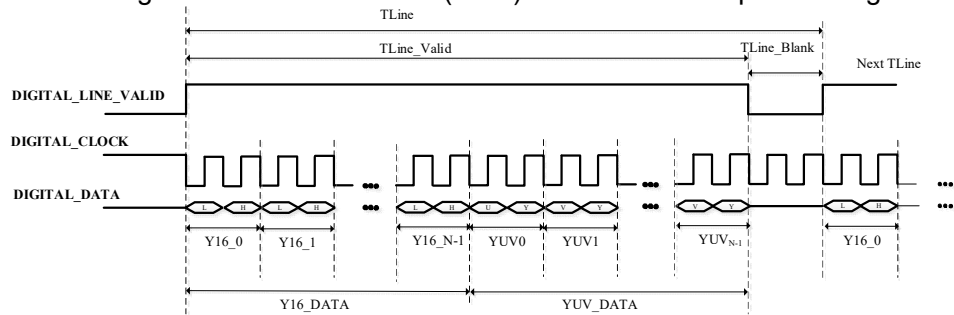


Figure 2-5b YUV422+Y16 (LSB) row and data sequence diagram

2.3.1.2 CMOS8 with parameter line

8bits parallel digital video timing parameters (with parameter line) are shown in Table 2-6, Table 2-7.

Table 2-6 Digital port 8bit sequence parameters (with parameter line)(30HZ)

| Video format | 30Hz (Y16/YUV422) | | | 30Hz (Y16+YUV422) | | |
|--------------|----------------------|------|-------------|----------------------|------|-------------|
| | Typical value | Unit | Description | Typical value | Unit | Description |
| Resolution | 640*515 | | | 1280*515 | | |
| NW | 640 | | | 1280 | | |
| NH | 515 | | | 515 | | |
| DIGITAL_CLK | 21.75 | MHz | | 43.75 | MHz | |
| TLine | 62.20 | us | 1352CLK | 62.20 | us | 2704 CLK |
| TLine Valid | 58.85 | us | 1280 CLK | 58.85 | us | 2560 CLK |
| TLine Blank | 3.34 | us | 72 CLK | 3.34 | us | 144 CLK |
| TPixel | 0.046.. | us | 1 CLK | 0.023.. | us | 1 CLK |
| TStart | / | us | / | / | us | / |
| TFrame | 33.33 | ms | 536 Line | 33.33 | ms | 536 Line |
| TField Valid | 32.01 | ms | 515 Line | 32.01 | ms | 515 Line |
| TField Blank | 1.32 | ms | 21 Line | 1.32 | ms | 21 Line |

Table 2-7 Digital port 8bit sequence parameters (with parameter line)(25HZ)

| Video format | 25Hz (Y16/YUV422) | | | 25Hz (Y16+YUV422) | | |
|--------------|----------------------|------|----------|----------------------|------|----------|
| | Typical value | Unit | Remarks | Typical value | Unit | Remarks |
| Resolution | 640*515 | | | 1280*515 | | |
| NW | 640 | | | 1280 | | |
| NH | 515 | | | 515 | | |
| DIGITAL_CLK | 21.75 | MHz | | 43.5 | MHz | |
| TLine | 62.20 | us | 1352CLK | 62.20 | us | 2704CLK |
| TLine Valid | 58.85. | us | 1280 CLK | 58.85 | us | 2560 CLK |

| | | | | | | |
|--------------|---------|----|----------|---------|----|----------|
| TLine_Blank | 3.34 | us | 72 CLK | 16.18 | us | 144 CLK |
| TPixel | 0.046.. | us | 1 CLK | 0.023.. | us | 1 CLK |
| TStart | / | us | / | / | us | / |
| TFrame | 40 | ms | 643 Line | 40 | ms | 643 Line |
| TField_Valid | 32.01 | ms | 515 Line | 32.01 | ms | 515 Line |
| TField_Blank | 7.99 | ms | 128 Line | 7.99 | ms | 128 Line |

The frame timing of 8bits parallel data for Y16/YUV422 with parameter line is shown in Figure 2-6.

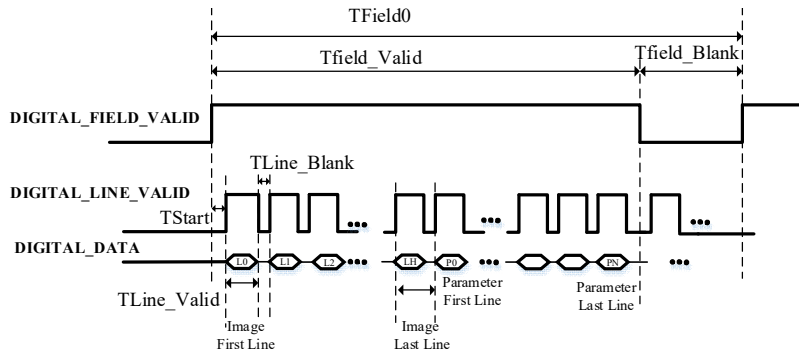


Figure 2-6 Y16/YUV422 + parameter line timing diagram

The timing of 8bits parallel data for Y16 + parameter line is shown in Fig. 2-7.

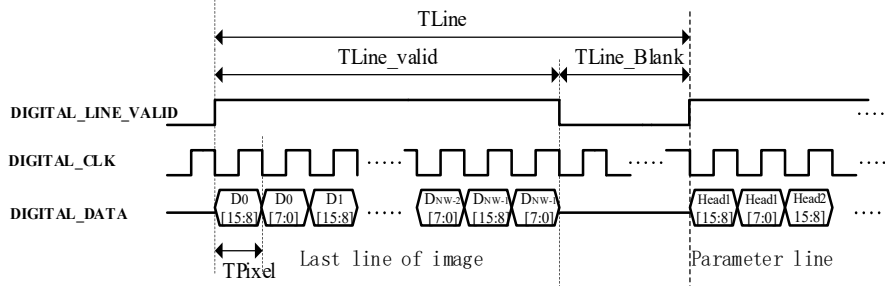


Figure 2-7a Y16+ parameter line (MSB) timing diagram

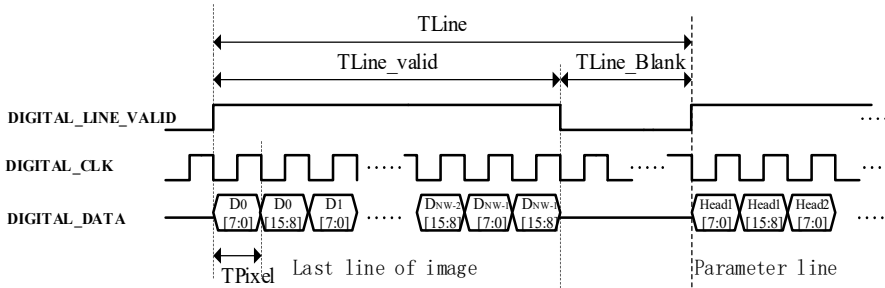


Figure 2-7b Y16+ parameter line (LSB) timing diagram

The timing of 8bits parallel data for YUV422 + parameter line is shown in Fig. 2-8.

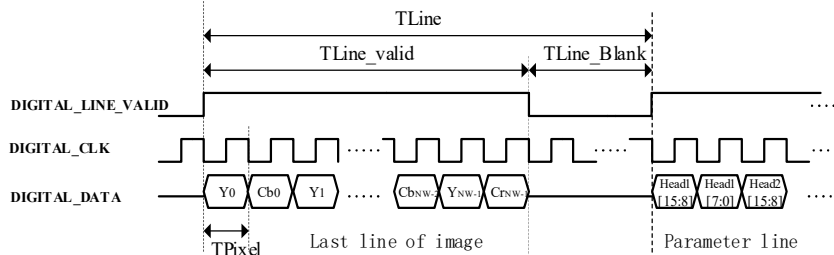


Figure 2-8a YUV422+ parameter line (MSB) timing diagram

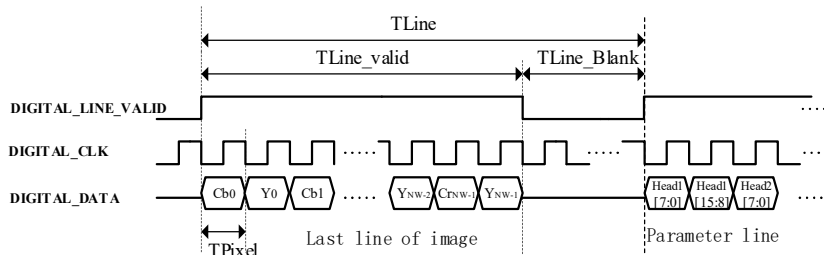


Figure 2-8b YUV422+ parameter line (LSB) timing diagram

The timing diagram of the data source as the Y16 parameter line YUV422 is shown in Figure 2-9 (CMOS8):

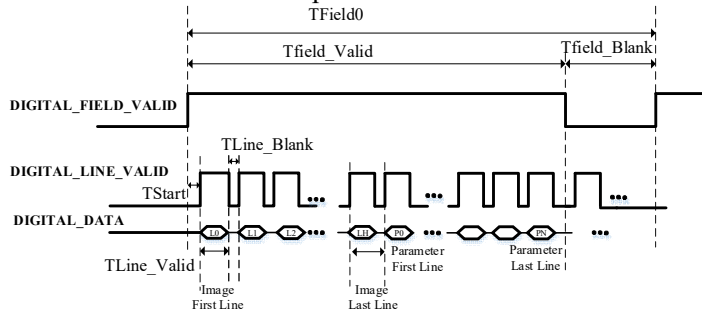


Figure 2-9a Line timing diagram of the a YUV422+Y16+ parameter line

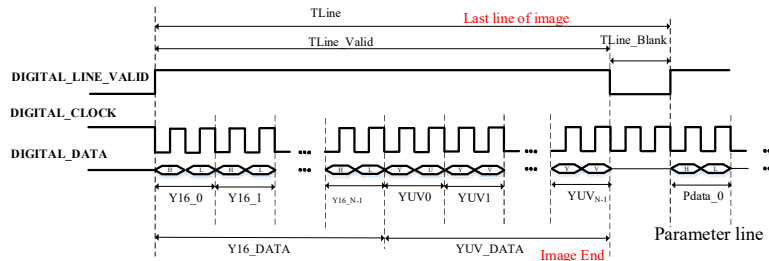


Figure 2-9b YUV422 +Y16 (MSB)+ parameter line

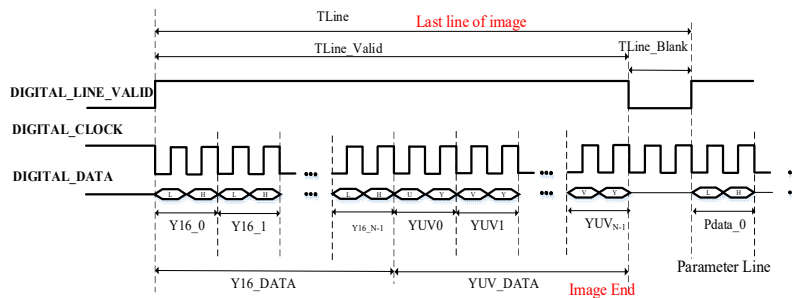


Figure 2-9c YUV422 +Y16 (LSB)+ parameter line

2.3.2 16bits parallel data (CMOS16)

2.3.2.1 CMOS16 without parameter line

The timing parameters of 16bits parallel data are shown in Table 2-8, Table 2-9.

Table 2-8 16bits parallel data timing parameters 1(without parameter line) (30HZ)

| Video format | 30Hz (Y16/YUV422) | | | 30Hz (Y16+YUV422) | | |
|--------------|----------------------|------|---------|----------------------|------|---------|
| | Typical value | Unit | Remarks | Typical value | Unit | Remarks |
| Resolution | 640×512 | | | 1280*512 | | |
| NW | 640 | | | 1280 | / | / |
| NH | 512 | | | 512 | / | / |

| | | | | | | |
|--------------|---------|-----|----------|---------|-----|----------|
| DIGITAL_CLK | 10.875 | MHz | | 21.75 | MHz | / |
| TLine | 62.20 | us | 676CLK | 62.20 | us | 1352 CLK |
| TLine_Valid | 58.85 | us | 640 CLK | 58.85 | us | 1280 CLK |
| TLine_Blank | 3.34 | us | 36 CLK | 3.34 | us | 72 CLK |
| TPixel | 0.092.. | us | 1 CLK | 0.046.. | us | 1 CLK |
| TStart | / | us | / | / | us | / |
| TFrame | 33.33 | ms | 536 Line | 33.33 | ms | 536 Line |
| TField_Valid | 31.84 | ms | 512 Line | 31.84 | ms | 512 Line |
| TField_Blank | 1.49 | ms | 24Line | 1.49 | ms | 24 Line |

Table 2-9 16bits parallel data timing parameters 1(without parameter line)(25HZ)

| Video format | 25Hz (Y16/YUV422) | | | 25Hz (Y16+YUV422) | | |
|--------------|----------------------|------|----------|----------------------|------|----------|
| | Typical value | Unit | Remarks | Typical value | Unit | Remarks |
| Resolution | 640*512 | | | 1280*512 | | |
| NW | 640 | | | 1280 | | |
| NH | 512 | | | 512 | | |
| DIGITAL_CLK | 10.875 | MHz | | 21.75 | MHz | |
| TLine | 62.20 | us | 676CLK | 62.20 | us | 1352 CLK |
| TLine_Valid | 58.85 | us | 640 CLK | 58.85 | us | 1280 CLK |
| TLine_Blank | 3.34 | us | 36 CLK | 3.34 | us | 72 CLK |
| TPixel | 0.092 | us | 1 CLK | 0.046.. | us | 1 CLK |
| TStart | / | us | / | / | us | / |
| TFrame | 40 | ms | 643 Line | 40 | ms | 643 Line |
| TField_Valid | 31.84 | ms | 512 Line | 31.84 | ms | 512 Line |
| TField_Blank | 8.16 | ms | 131 Line | 8.16 | ms | 131 Line |

The frame timing of 16bits parallel data for Y16/YUV422 is shown in Figure 2-10.

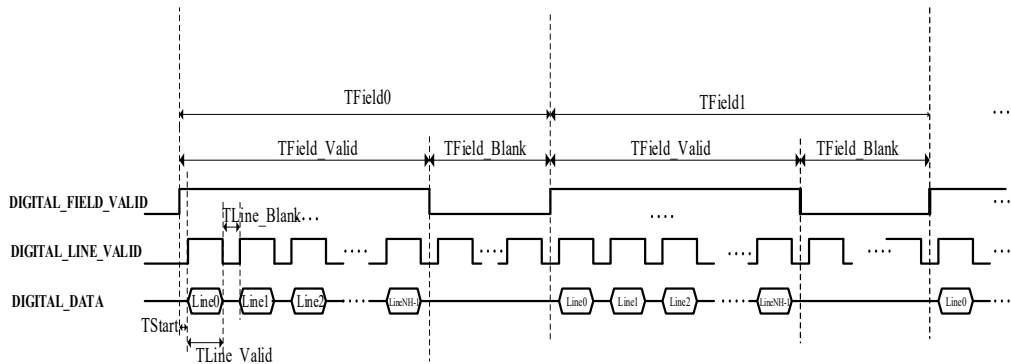


Figure 2-10 CMOS16, 16bits parallel data without parameter line timing diagram

The timing of 16bits parallel data for Y16 is shown in Figure 2-11.

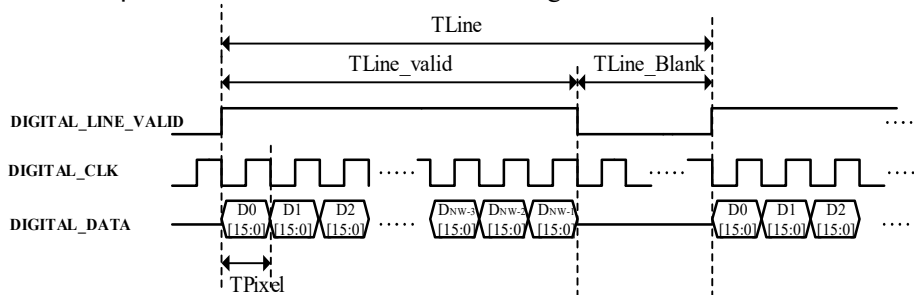


Figure 2-11 CMOS16, Y16 timing diagram

The timing of 16bits parallel data for YUV422 is shown in Figure 2-12.

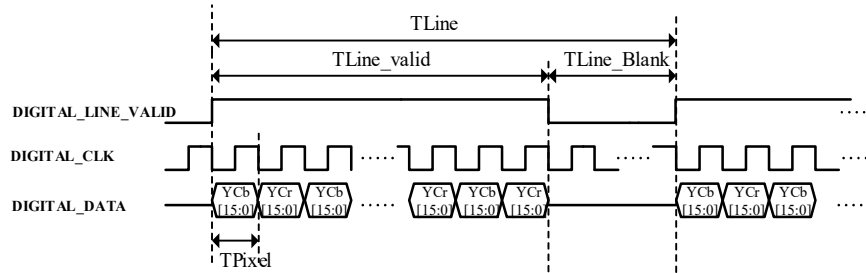


Figure 2-12 CMOS16, YUV422 timing diagram

The timing of row and data timing with YUV422+Y16 is shown in Figure 2-13.

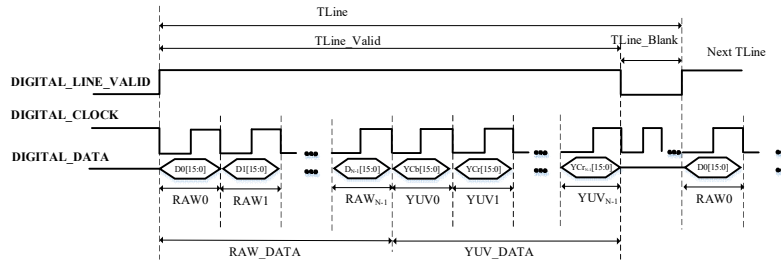


Figure 2-13 CMOS16 YUV422 +Y16 row and data time sequence diagram

2.3.2.2 CMOS16 with parameter line

16bits parallel data (including parameter line) timing parameters are shown in Table 2-10, Table 2-11.

Table.2-10 16bits parallel data timing parameters 1 (with parameter line)(30HZ)

| Video format | 30Hz (Y16/YUV422) | | | 30Hz (Y16/YUV422) | | |
|--------------|----------------------|------|-------------|----------------------|------|-------------|
| | Typical value | Unit | Description | Typical value | Unit | Description |
| Resolution | 640*515 | | | 1280*515 | | |
| NW | 640 | | | 1280 | / | / |
| NH | 515 | | | 515 | / | / |
| DIGITAL_CLK | 10.875 | MHz | | 21.75 | MHz | / |
| TLine | 62.20 | us | 676CLK | 62.20 | us | 1352CLK |
| TLine_Valid | 58.85 | us | 640CLK | 58.85 | us | 1280CLK |
| TLine_Blank | 3.34 | us | 36CLK | 3.34 | us | 72 CLK |
| TPixel | 0.092.. | us | 1 CLK | 0.046.. | us | 1 CLK |
| TStart | / | us | / | / | us | / |
| TFrame | 33.33 | ms | 536 Line | 33.33 | ms | 536 Line |
| TField_Valid | 32.01 | ms | 515 Line | 32.01 | ms | 515 Line |
| TField_Blank | 1.32 | ms | 21 Line | 1.32 | ms | 21 Line |

Table.2-11 16bits parallel data timing parameters 1 (with parameter line)(25HZ)

| Video format | 25Hz (Y16/YUV422) | | | 25Hz (Y16+YUV422) | | |
|--------------|----------------------|------|----------|----------------------|------|----------|
| | Typical value | Unit | Remarks | Typical value | Unit | Remarks |
| Resolution | 640*515 | | | 1280*515 | | |
| NW | 640 | | | 1280 | | |
| NH | 515 | | | 515 | | |
| DIGITAL_CLK | 10.875 | MHz | | 21.75 | MHz | |
| TLine | 62.20 | us | 676CLK | 62.20 | us | 1352 CLK |
| TLine_Valid | 58.85 | us | 640 CLK | 58.85 | us | 1280 CLK |
| TLine_Blank | 3.34 | us | 36 CLK | 3.34 | us | 72 CLK |
| TPixel | 0.092 | us | 1 CLK | 0.046.. | us | 1 CLK |
| TStart | / | us | / | / | us | / |
| TFrame | 40 | ms | 643 Line | 40 | ms | 643 Line |

| | | | | | | |
|--------------|-------|----|----------|-------|----|----------|
| TField_Valid | 32.01 | ms | 515Line | 32.01 | ms | 515Line |
| TField_Blank | 7.99 | ms | 128 Line | 7.99 | ms | 128 Line |

The frame timing of 16bits parallel data for Y16/YUV422 with parameters line is shown in Figure 2-14.

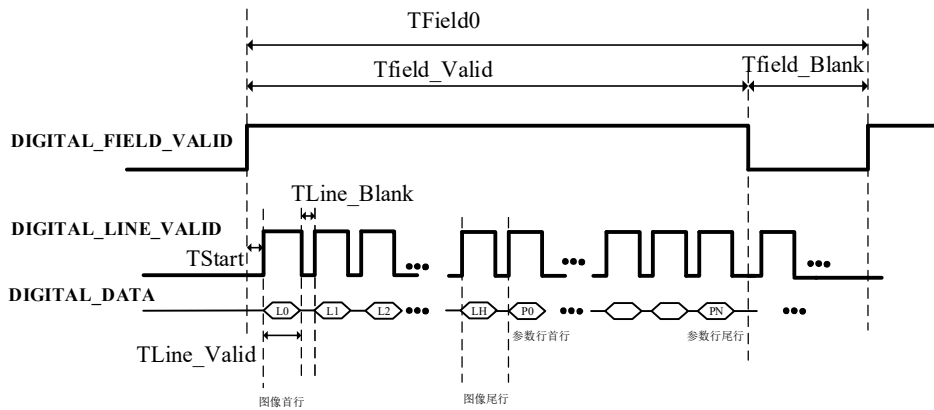


Figure 2-14 Y16/YUV422+parameter frame timing diagram

The timing of 16bits parallel data for Y16 with parameters line is shown in Figure 2-15.

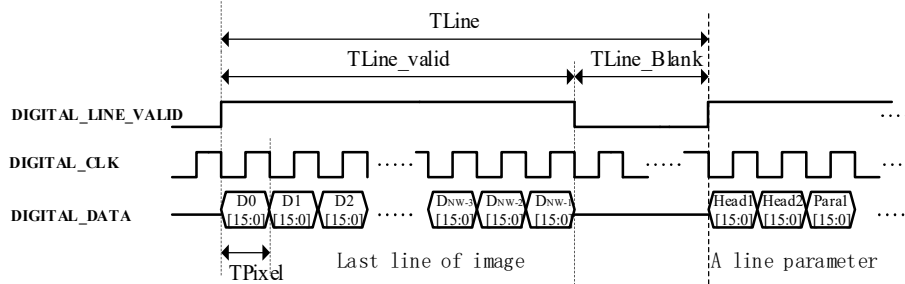


Figure 2-15 CMOS16 Y16+parameter timing diagram

The timing of 16bits parallel data for YUV422 with parameters line is shown in Figure 2-16.

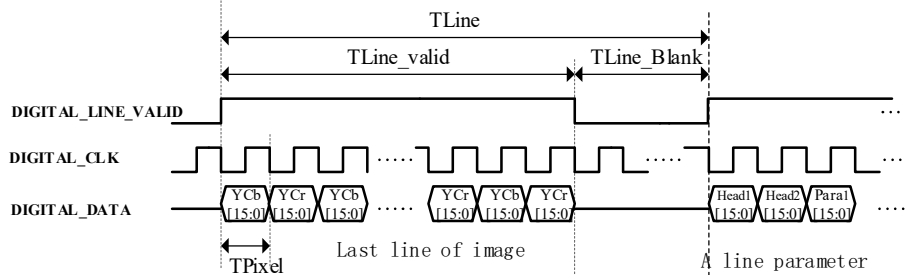


Figure 2-16 CMOS16, YUV422+parameter timing diagram

The timing of row and data timing graph with YUV422 Y16 parameter lines is shown in Figure 2-17.

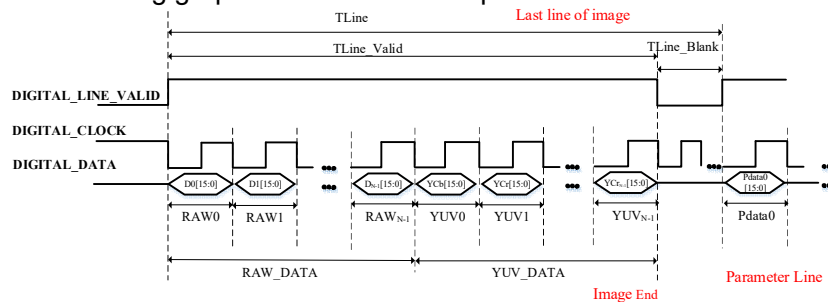


Figure 2-17 CMOS16 YUV422+Y16+parameter row and data timing diagram

2.3.3 Description of BT.656 format

The BT.656 interface output data are standard BT.656 format.

- 1) Data format: Cb, Y, Cr, Y or Y, Cb, Y, Cr 8bit.
- 2) Progressive mode is supported, interlaced mode is not supported.
- 3) Bt.656 can be configured based on the resolution size to customize the number of hidden and total rows.
- 4) Only support frame transmission, the same frame does not support two field transmission.
- 5) Internal synchronization of BT.656: the figure below shows the format of Internal synchronization.

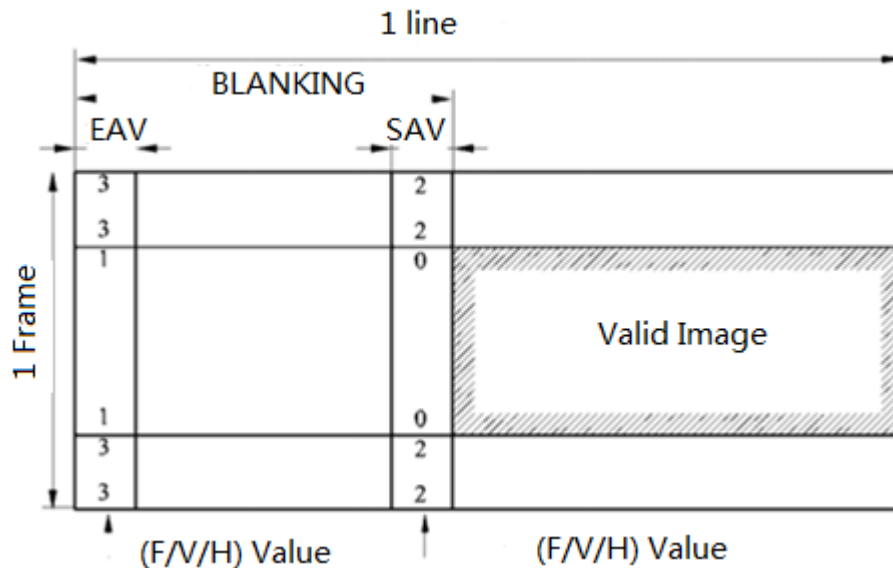


Figure 2-18: BT.656 interface output data format

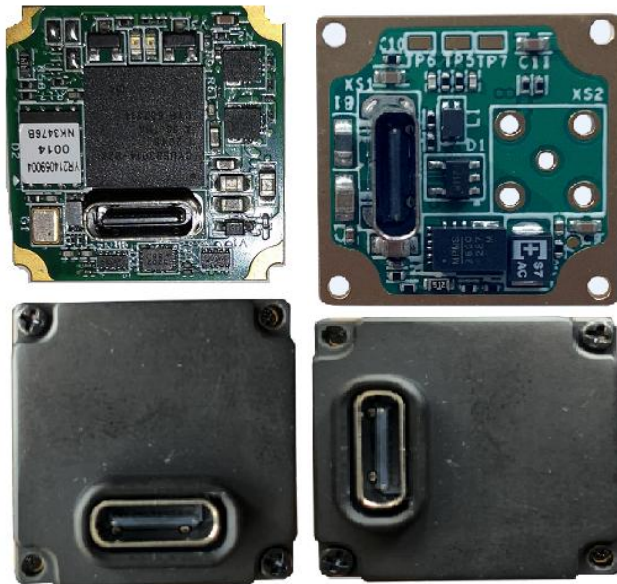
3 Optional Accessories



Type-C VPC board



Adapter + Video cable + Micro USB cable



Type-C USB2.0 board Type-C USB3.0 board

3.1 VPC expansion board

3.1.1 Feature of the board

- Type-C USB interface.
- Steady current $\leq 300\text{mA}@5\text{V}$, transient starting current $\leq 500\text{mA}@5\text{V}$.
- Serial baud rate: 115200(8N1).
- analog video output, 75Ω characteristic impedance.
- Hot swap protection.

3.1.2 Application instruction for VPC board

VPC board has two external interfaces: analog video interface and Type-C USB interface.

The user can use the optional video extension cable for the application of external analog video, with one terminal (MCX terminal) connected to the module and the other terminal connected to the AV interface of monitor.

The user can also use the optional USB cable or mobile phone USB cable with rated current over 1A , with one terminal connected to the Type-C USB interface of the module and the other terminal connected to the USB interface of the computer.

After the ICC control software is installed on the computer, the connection between the module and the ICC software can be realized through the USB cable. For the installation instructions of the ICC control software, please refer to ICC related instructions .

3.2 USB2.0 expansion board

3.2.1 Feature of the board

- Standard type-C interface interface;
- Steady state current $\leq 350\text{mA}@5\text{V}$, Starting transient current $\leq 500\text{mA}@5\text{V}$ (with the module);
- Serial baud rate:115200;
- Supporting UVC video transmission protocol;
- Support USB port hot plug protection;

3.2.2 Application description

USB2.0 expansion board is a digital video acquisition board for TWIN612 standard infrared thermal imaging movement. It adopts USB2.0 standard and type-c interface. It supports digital video transmission and serial port control. It is portable, universal and easy to develop and integrate.

ICC (infrared camera controller) software is supported. The movement can be configured and the digital video output can be viewed through the control software. ICC software version 1.3.0 and above.

Operating system: support Windows 7 / 8 / 10 / XP, etc.

Language environment: support Chinese / English, etc.

For detailed application method, please refer to "USB expansion board instructions - v1.0".

3.3 USB3.0 expansion board

3.3.1 Feature of the board

- Standard type-C interface interface;
- Steady state current $\leq 350\text{mA}@5\text{V}$, Starting transient current $\leq 500\text{mA}@5\text{V}$ (with the module);
- Serial baud rate:115200;
- Supporting UVC video transmission protocol;
- Support USB port hot plug protection;

3.3.2 Application description

USB3.0 expansion board is a digital video acquisition board for TWIN612 standard infrared thermal imaging movement. It adopts USB3.0 standard and type-c interface. It supports digital video transmission and serial port control. It is portable, universal and easy to develop and integrate.

ICC (infrared camera controller) software is supported. The movement can be configured and the digital video output can be viewed through the control software. ICC software version 1.3.0 and above.

Operating system: support Windows 7 / 8 / 10 / XP, etc.

Language environment: support Chinese / English, etc.

For detailed application method, please refer to "USB expansion board instructions - v1.0".

4 ICC control software

4.1 Installation instructions

This chapter mainly describes the installation method, steps and precautions of the infrared module software to achieve the normal use of the installed software.

1. Firstly, double-click the application installation file  setup.exe for installation to pop up an installation window, click the button "Next" for installation at the next step, as shown in Figure 4-1.



Figure 4-1 Software installation interface 1

2. Click the button "Next" to pop up a window for selection of installation path and the installation object. After selecting the file installation path and object, click the button "Next" to proceed to the next step, as shown in Figure 4-2.

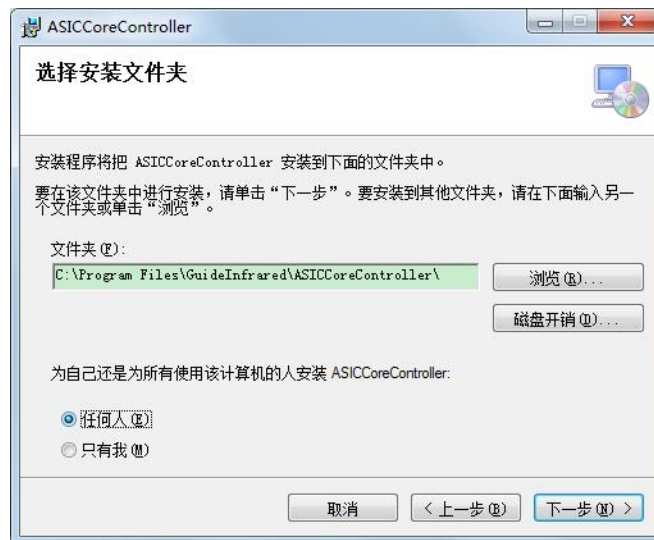


Figure 4-2 Software installation interface 2

3. In the new pop-up window, click the button "Next" to proceed to the next step, as shown in Figure 4-3.

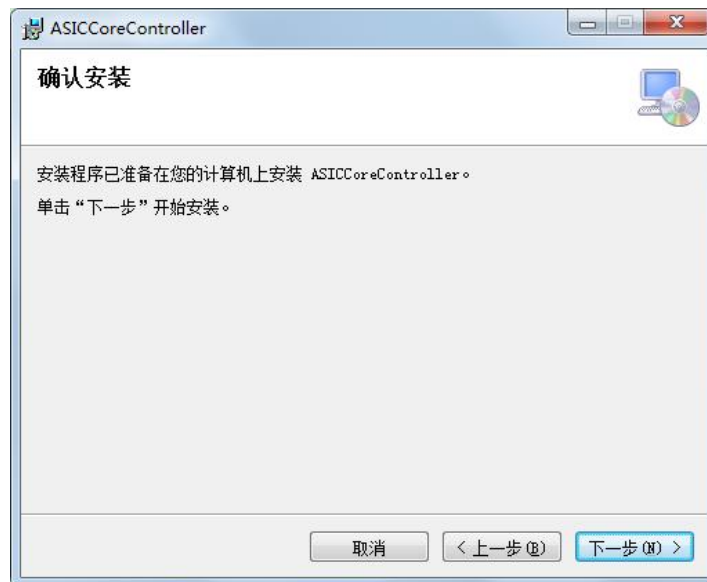


Figure 4-3 Software installation interface 3

4. During installation, the installation progress interface will appear, please wait for the installation to complete, as shown in Figure 4-4.

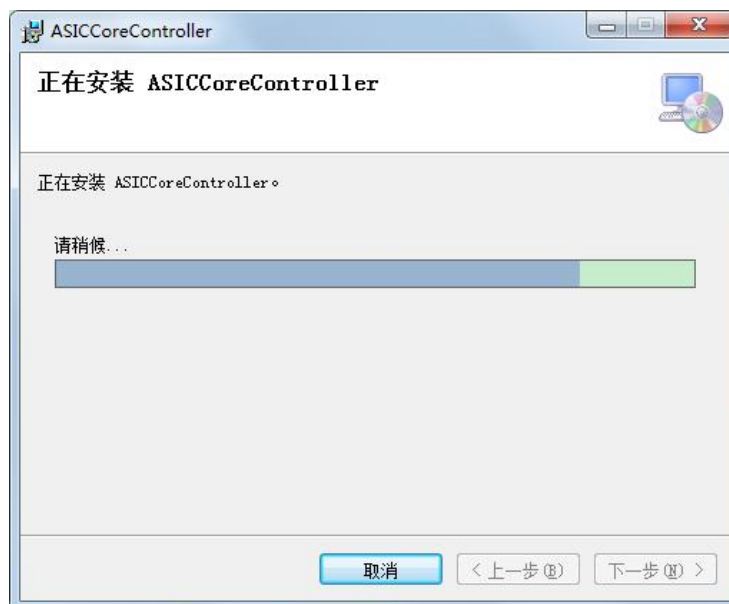


Figure 4-4 Software installation interface 4

5. After the installation, two windows will pop up, one is the window for installation complete, and other one is window for USB driver, as shown in Figure 4-5 and Figure 4-6 respectively.



Figure 4-5 Pop-up window for software installation complete



Figure 4-6 Pop-up window for USB driver installation

6. Click the button "Close" in Figure 4-5 to complete the module software installation, and then click the button "Next" in Figure 4-6 for USB driver installation, at which time, an agreement selection window as shown in Figure 4-7 will pop up.

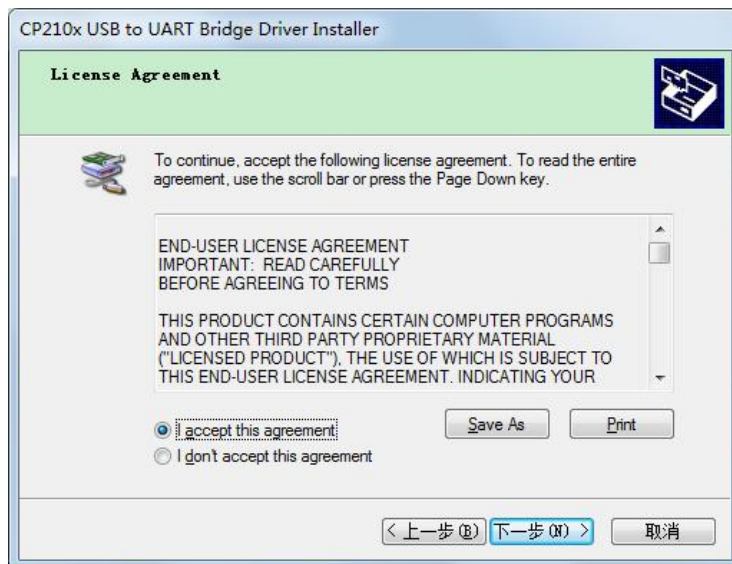


Figure 4-7 Agreement selection window

7. Select the button "I accept this agreement" and click the button "Next" to continue the installation.
8. During installation, the installation progress interface will appear, please wait for the installation to complete, as shown in Fig. 4-8.

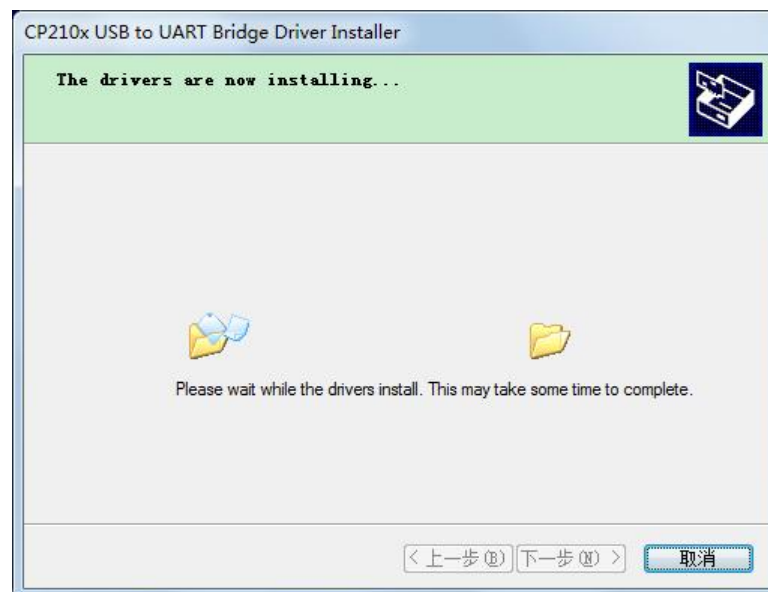


Figure 4-8 Installing window

9. Upon USB driver installation, an installation complete window as shown in Figure 4-9 will pop up.

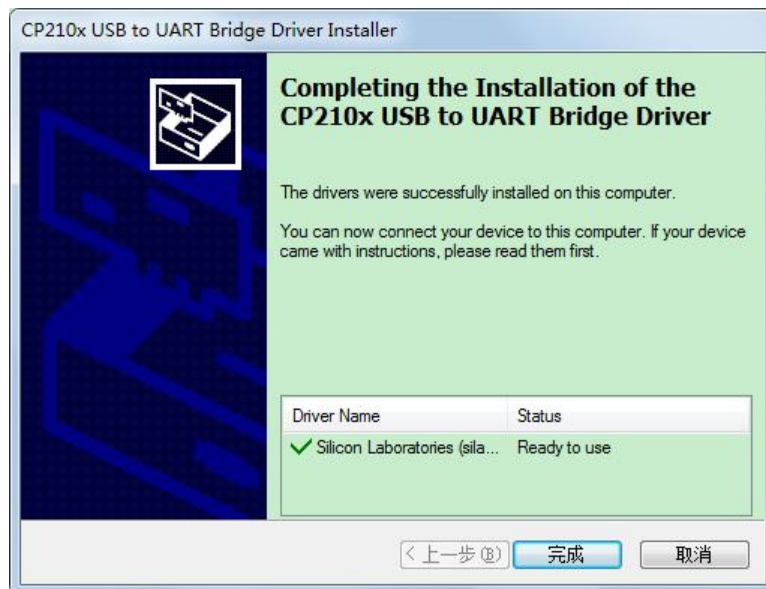



Figure 4-9 Pop-up window for USB installation complete

10. Click the button "Finish", installation complete, quit the installation.

4.2 Interconnection between module and PC control software

This chapter describes how to use the infrared module software to connect the PC and the module through a USB cable.

1. Click the desktop icon  or click the "ASIC Core Controller" in "Start" to start the infrared module software.
2. When the software is opened for the first time, the connection wizard interface is an English interface by default, the upper left corner shows that the current connection status is "NotConnected", and the upper right corner shows the software version number, as shown in Figure 4-10.

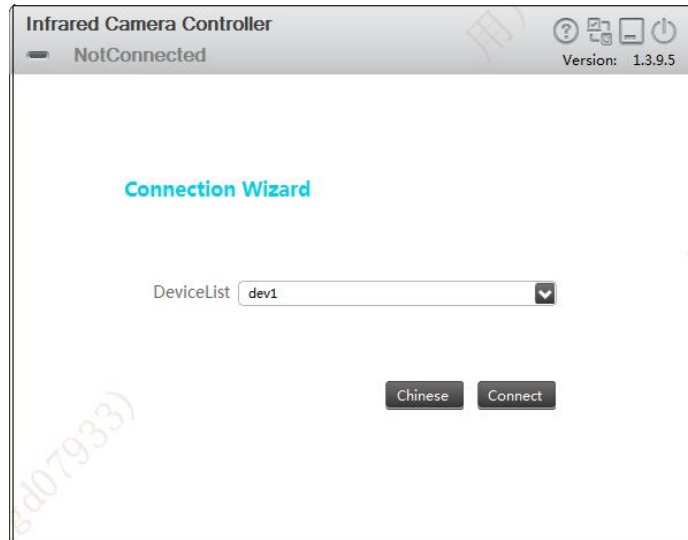






Figure 4-10 Connection wizard interface

3. Click the icon  in the upper left corner to display the software instructions;
Click the icon  to switch to the connection wizard interface;
Click the icon  to hide the window in the taskbar;
Click the icon  to close the software.

4. Operation instructions of PC control software

After the module and PC control software are connected successfully, the module enters the operation interface. The functions and operation method of the interface will be described in the following section.

4.2.1 Status

This chapter mainly describes the parameters and performance status of the module connected at present.

1. Click the "Connect" to communicate with the module successfully, and then allow the software to enter the module status interface. The upper left corner of the interface shows the current connection status and module type, as shown in Figure 4-11.



Figure 4-11 Module status interface

2. The interface shows the module information, including name, shape, detector type, wavelength, resolution, function, input voltage, communication protocol and machine code., etc. The program version number, focal plane array temperature, and current communication baud rate of the slave are also displayed at the bottom of the interface.

4.2.2 Settings

This chapter mainly describes the setting of the shutter including compensation interval time, Image mode including image freeze, all kinds of test image.

Click the setting menu on the left side of the interface to enter the module settings interface as shown in Figure 4-12.

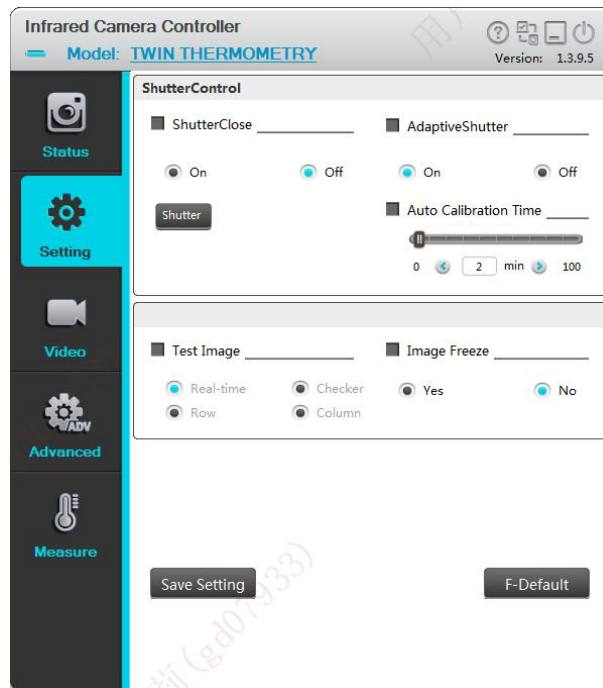
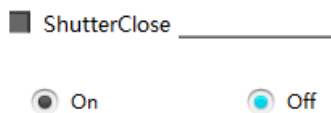
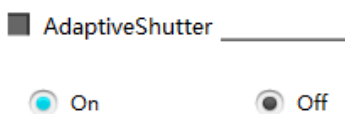


Figure 4-12 Module settings interface

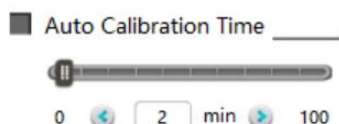
Shutter closure: When the shutter closure is closed, select Shutter Compensation button to do shutter compensation.



Adaptive compensation: on or off.



Automatic compensation time: Set the time interval (in minutes) of automatically opening the shutter. When the module is just started and the focal plane temperature is not stable, the time interval may be short. After the focal plane temperature is stable, you can extend the time interval properly.



Test Image: the test patterns include real-time、checker, row and column scanning pattern. The twin412 only supports real-time test screens by default.

Test Image _____

Real-time Checker
 Row Column

Image freeze: For the analog video scene of interest, you can select “Yes” to freeze the infrared scene image. Then the infrared image of the analog video output will not change as the scene does, allowing users to watch the scene of interest. You can choose “No” to unfreeze, to observe real-time changes in the scene.

Image Freeze _____

Yes No

Save settings: After using the Infrared Camera Controller ICC to change the module mode and parameter values, click the button "Save Settings" to save the current configuration as the new power-on default. When powering on the module at the next time, the module will be configured with the new power-on default. If you do not save the settings, the change made by ICC is only valid for the current stage, and the module will be configured based on the previous default at the next boot.

Factory reset: Press the button “Factory Reset” to restore module's all configurations to the factory defaults.

4.2.3 Video

This section describes the parameters adjustment and image processing of analog video, digital video and other related algorithms in detail.

4.2.3.1 Setting interface of analog video

Click the video menu on the left side of the interface, and enter the analog video setting interface, as shown in Fig. 4-13.

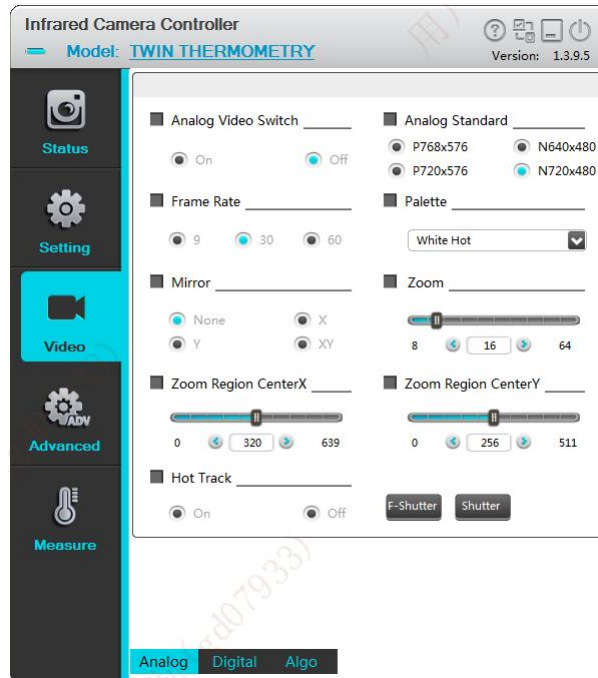
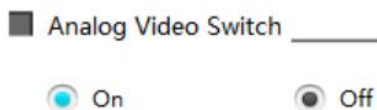


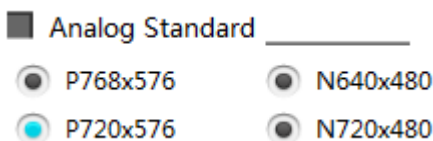
Figure 4-13 The setting interface of analog video

The analog video page mainly includes: analog video switch, system selection, frame rate setting, polarity/pseudo-color, mirror and zoom setting.

Analog video switch: If the analog video display is not needed in the application, you can set the switch “off” to turn off the analog video to reduce 200mW power consumption. The is “on” by default.



Video system: Choose the video system to output. The module provides two video systems: PAL (video resolution 768×576/720×576, valid resolution 640×512) and NTSC (video resolution 640×480/720×480, valid resolution 640×480). Different output systems correspond to different digital and analog video frame rate. After changing the video system, the module needs to be restarted after shut down.

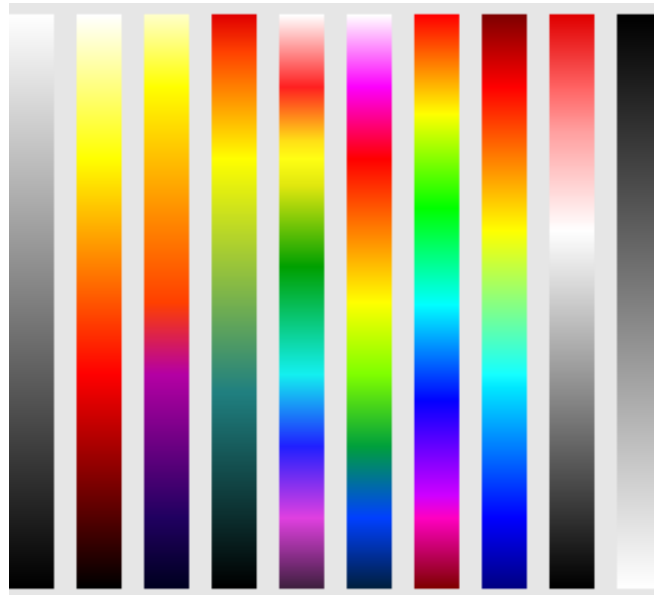


Frame rate: Select the frame rate of the analog video output for the module. If the module is working under PAL system, the frame rate of the analog video can be set to 25Hz. If the module is working under NTSC system, the frame rate of the analog video can be set to 30Hz. The lower the frame rate is, the lower the frequency needed to discover analog video motion is.

■ Frame Rate _____

9 30 60

Polarity/pseudo color: The module detects and images the temperature, and maps the temperature to the range between 0 and 255. In black white mode, the gray scale 0 is shown as solid black and the gray scale 255 is shown as white. In the gray scale range of 0~255, color mapping can be performed through the internal lookup table, and different lookup table represent different ribbons. The modes black hot (darker represents hotter) and white hot (whiter represents hotter) are often selected, and such simple temperature black white mapping is also known as polarity. Color mapping can also be performed through the color lookup table. The module provides totally nine color mapping, including white hot and black hot, which are suitable for analog and digital video.



■ Palette _____

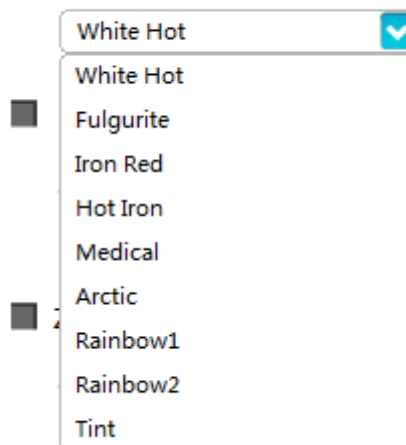


Figure 4-14 Pseudo-color table

Zoom: 8~64 Optional, step is 1.

■ Zoom _____

8 8 64

■ Zoom Region CenterX _____

0 320 639

■ Zoom Region CenterY _____

0 256 511

4.2.3.2 The digital video

Click digital video menu at the bottom of Fig. 4-13, and enter the digital video setting interface, as shown in Fig. 4-15.

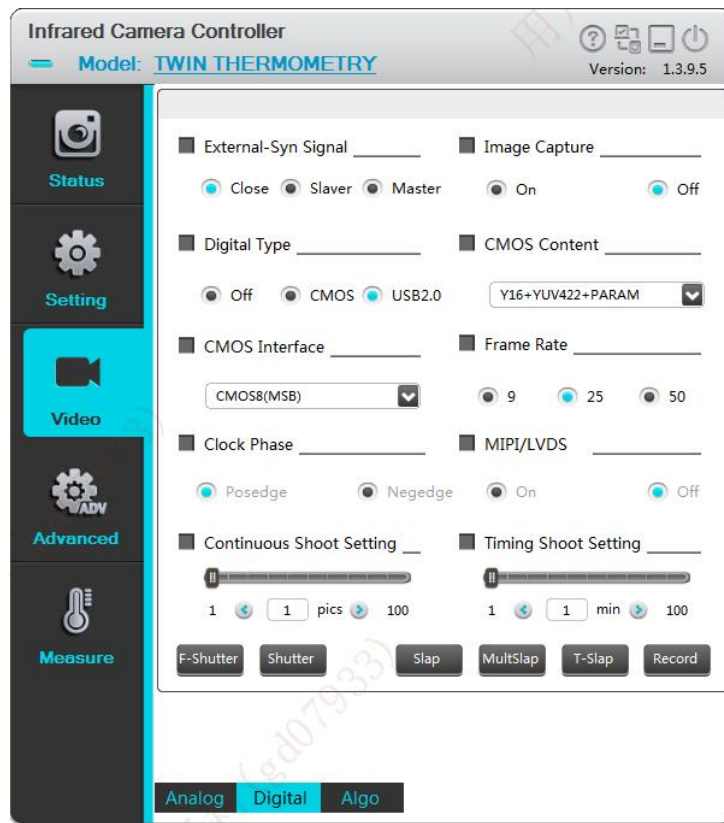


Figure 4-15 The setting interface of digital video

Digital video page is mainly used to achieve the related settings of digital video, such as external synchronization (slave mode) switch, digital port switch, digital port type, CMOS content, CMOS interface, digital frame rate and LVDS switch .

External synchronization: the movement external synchronization from the mode switch.



Slave: When the module is working, start external synchronization mode. If the external synchronization trigger signal is detected, that is, output video according to the external synchronization signal after the end of the current field. If the external synchronization signal is not detected, execute it in the last cycle.

The specific timing can be designed according to the actual situation.

Off: the movement works in self-synchronous mode, normal output video.

Main: The output field periodic signal is used for external synchronization.

Digital port type: select the output format of digital parallel port, including CMOS and USB2.0.

If you select CMOS, you also need to configure the select CMOS content and CMOS interface options.

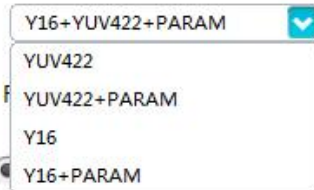
If you select the USB2.0, the digital port will directly output the USB2.0 video.

■ Digital Type _____

Off CMOS USB2.0

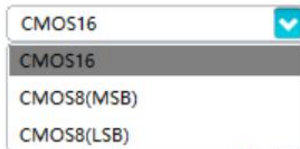
CMOS content: To select CMOS content. The CMOS content can only be configured when the digital port type option is “CMOS”. CMOS content can be set as follows, and please refer to Section 2.3 for the digital port output timing. Each time you change the CMOS content, reopen the digital port for the changes to take effect.

■ CMOS Content _____



CMOS interface: To select CMOS interface. The CMOS content can only be configured when the digital port type option is “CMOS”. The CMOS interface selection is as follows, and please refer to Section 2.3 for the digital port output timing. Except for the interface CMOS16, the other two interfaces can't support the real time video display.

■ CMOS Interface _____



Frame rate: To set the digital video CMOS type output frame rate.

If the Firmware version is 25/30hz, the frame rate of digital video can be set to 30Hz, 25Hz and 9Hz.

If the Firmware version is 50/60hz , the frame rate of digital video can be set to 60Hz, 50Hz and 9Hz.

The smaller the frame frequency setting of digital video is, the smaller the frame frequency of the field synchronization signal can be detected..

■ Frame Rate _____

9 30 60

Clock phase: default posedge.

■ Clock Phase _____

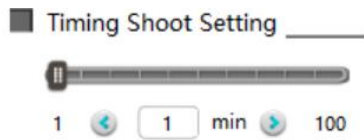
Posedge Negedge

MIPI/LVDS: LVDS switch setting. When setting to “On”, the module will output standard LVDS timing from the fixed interface. The default setting is “Off”.

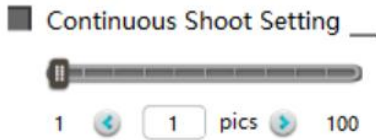
■ MIPI/LVDS _____

On Off

Time-lapsed photography interval: Set the time interval for the software to take photos of the captured video in unit of min.



Number of continuous shooting: Set the number of pictures taken from the captured video by the software.



Scene compensation: Click the button **F-Shutter** to capture the current scene data for non-uniformity correction.

Shutter compensation: Click the button **Shutter** to control the shutter close and to collect the shutter data for non-uniformity correction.

Shooting: Click the **Slap** button to take a screenshot of the current scene, and the picture is named after the current time and saved in the selected folder. The format of saved photo files is bmp or raw, based on the digital port.

Continuous shooting: Click the **MultSlap** button to take a continuous picture of the video. According to the number value set by the "number of continuous shooting", take pictures of the current scene. The picture is named after the current time and saved in the selected folder. The format of saved photo files is bmp or raw, based on the digital port.

Time-lapsed photography: Click the **T-Slap** button for timed photographing. The module will take pictures with the time interval you've set. The picture is named after the current time and saved in the selected folder. The format of saved photo files is bmp or raw, based on the digital port.

Video: Click the **Record** button to begin videoing after the button brightens; click again, the button returns to normal state and it will stop videoing; Video files are named after the current time and saved in the selected folder. The format of saved video files is raw, based on the digital port.

4.2.3.3 Algorithm

Click the algorithm menu at the bottom of Figure 4-15, and enter the algorithm setting interface 1, as shown in Figure 4-16.

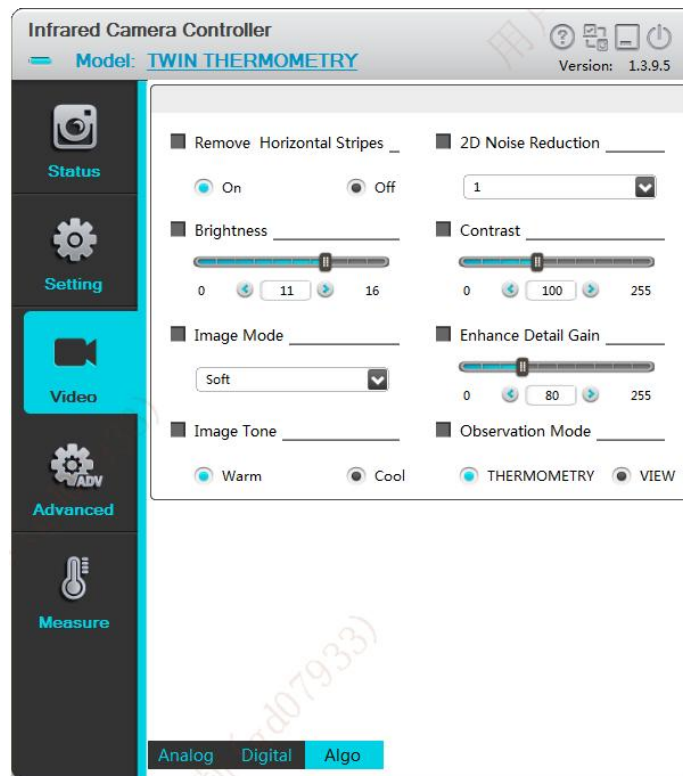
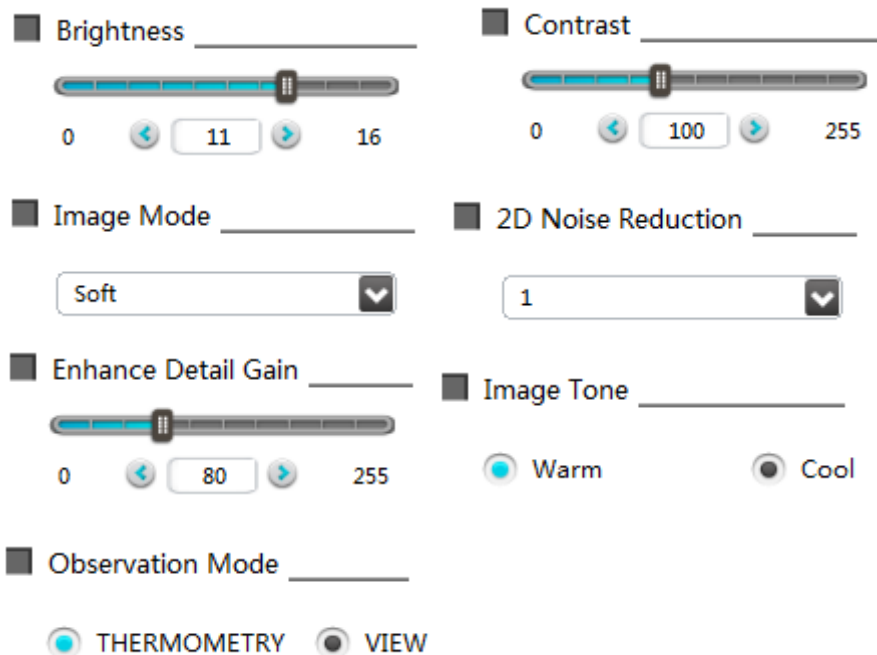


Figure 4-16 The algorithm setting interface 1

Brightness: Reflect the overall brightness of the image and adjust as a percentage. The larger the value is, the brighter the image will be.

Contrast: Reflect the overall size of the image contrast and adjust as a percentage. The larger the value is, the stronger the contrast will be.

Note. When Y8 correction is in automatic mode, brightness and contrast cannot be adjusted; When Y8 correction is in manual mode, brightness contrast can be adjusted.



4.2.4 Advanced Application

This chapter focuses on the advanced application operation of the module, including focusing, defective

pixel treatment, menu superposition and so on.

4.2.4.1 Focus setting interface

Click the advanced application menu at the left of interface, and enter the focus setting interface of advanced application, as shown in Figure 4-17.

This page mainly focus on the electric lens and updating program.

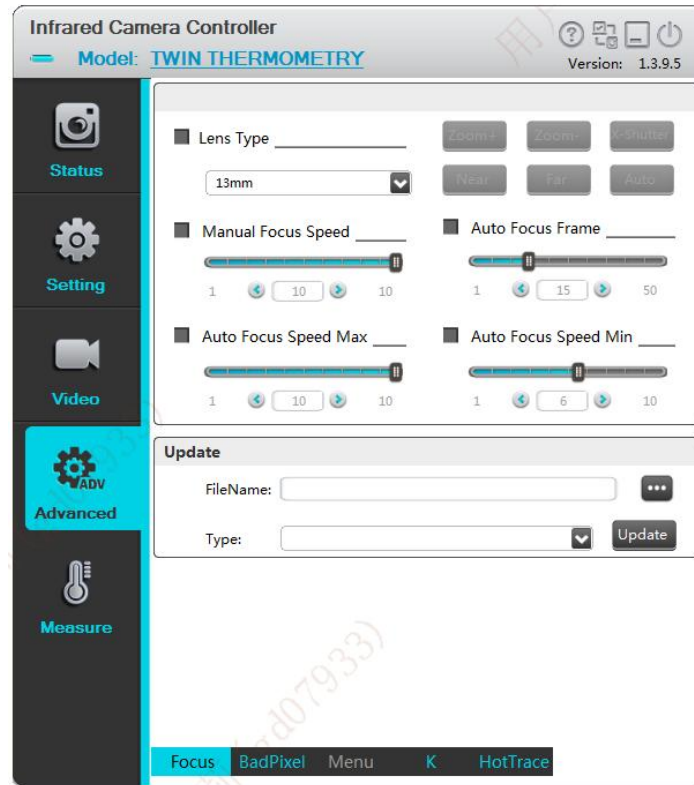


Figure 4-17 Advanced application interface

Focus : Unavailable for the module.

Updating program: Loading ".dat" file and select update type. Don't switch off during the updating program process

4.2.4.2 Defective pixel correction interface

Click the "Defective pixel" menu on the interface as shown in Figure 4-17, and enter the defective pixel correction interface of advanced application as shown in Figure 4-18.

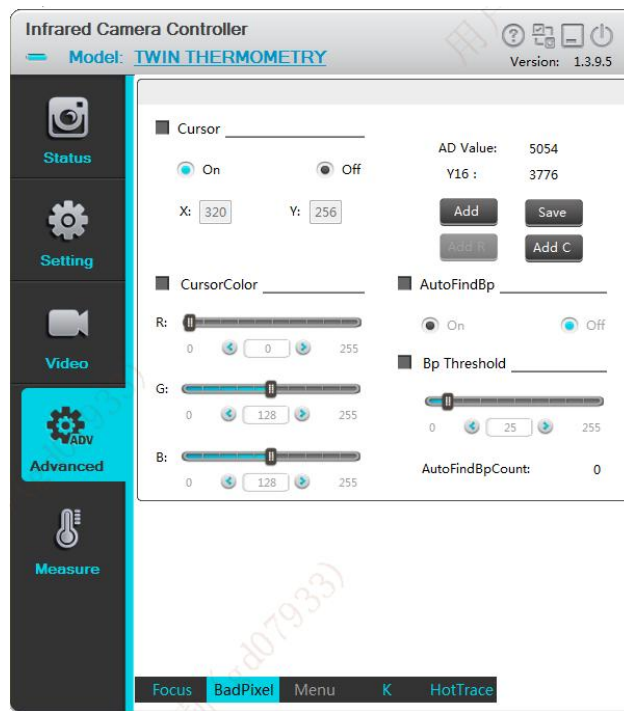


Figure 4-18 Defective pixel correction interface

On the defective pixel correction interface, imaging effects of the abnormal pixel of images can be corrected.

Cursor: Analog video cursor display switch. Cursor will be displayed at the corresponding location on the analog video when it is on. The cursor can be moved by adjusting the coordinates X and Y, or moved continuously via the arrow keys on keyboard. The AD sampling value of current coordinate point can also be displayed in real time.



AD value: display the AD sampling value of current coordinate to determine whether the current pixel is defective.

AD Value: 5054
Y16 : 3776

Y16: Displays the value of Y16 at the current coordinate

Coordinate X/Y: display the values of coordinate X/Y at current cursor location. The cursor can be moved continuously via Up and Down keys on the interface or arrow keys on the keyboard.

X: 320 Y: 256

Adding defective pixels: For the defective pixels of the detector pixel, you can move the cursor to a defective pixel, and click the "Add Defective Pixel" button to replace the selected defective pixel with a new pixel to improve image quality.

Saving defective pixels: After addition and replacement of the defective pixels / defective rows / defective columns, you can click "Save Defective Pixel" button to save the defective pixels, and the module will remember the positions of the saved defective pixels and replace them when you reboot the machine. Without saving the new defective pixels, the changes made through ICC are only valid in the current stage and the original defective pixels will be displayed at the same positions when you reboot the machine.

Add defective rows: Adds the rows where the cursor on as defective pixels, complete the whole row of defective pixels replacement.

Add defective columns: Adds the columns where the cursor on as defective pixels, complete the whole column of defective pixels replacement.

4.2.4.3 Menu OSD

Unavailable for the module.

4.2.4.4 Hot tracking

Click the font area of "hot trace" in the interface of Figure 4-17 and the software enters the interface of hot analysis in advanced applications. The first page of hot analysis is shown in Figure 4-19.

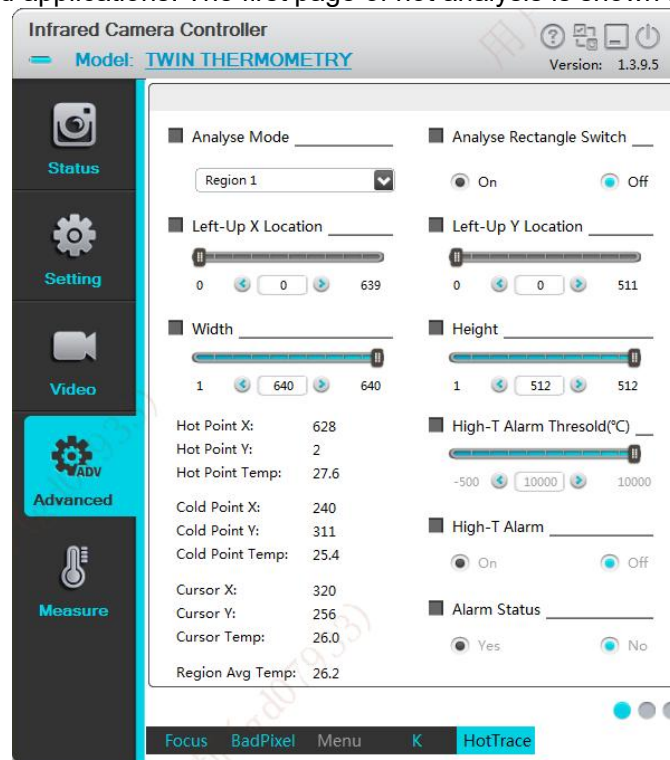
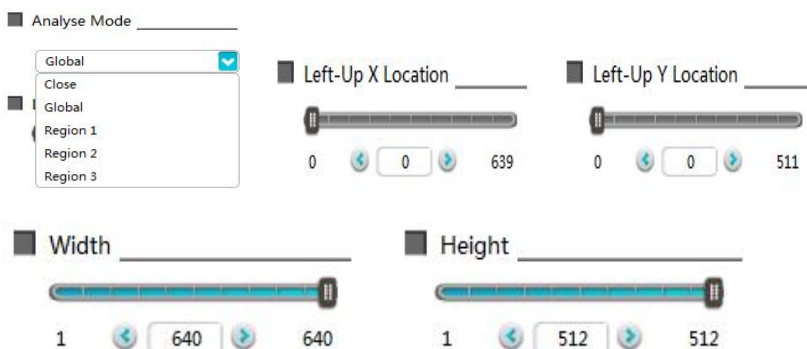


Figure 4-19 page 1 of Hot tracking

Analysis mode: region analysis mode selection



In the three regions of analysis mode, only one region can be selected for setting each time, but the parameters of three regions are independent. Three areas can not be displayed at the same time, also can not track or thermometry simultaneously. The area box displays off when you select analysis mode as off or full screen. After resetting the starting coordinates and width and height of the area, the area box displays the position, area tracking or thermometry immediately.

Analysis results display: the module is immediately tracked whether it is set to full screen or area. On

Up-Down: in this mode, pseudo-color is used to highlight the areas where the temperature or Y16 is higher than the upper limit threshold, and pseudo-color is used to highlight the areas where the temperature or Y16 is lower than the lower limit. The upper isotherm or lower isotherm mode can be realized by adjusting the threshold value.

Middle: In this mode, the areas where temperature or Y16 is larger than the upper threshold and smaller than the lower limit are highlighted with pseudo-color.

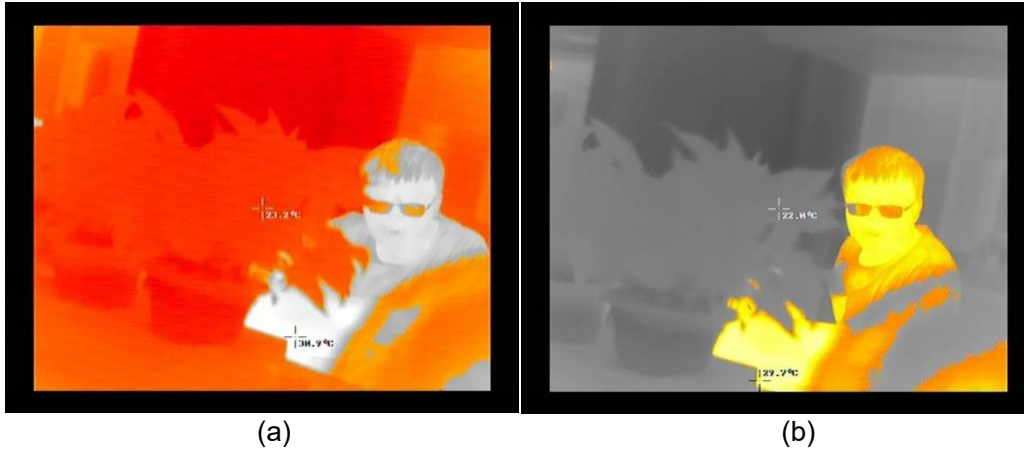


Figure 4-22 Isothermals

Take the thermography type as an example, the upper limit threshold is 39.0°C, the lower limit threshold is 29.0°C, FIG. a shows the upper and lower isothermal mode, and the scene beyond 29~39°C is represented by fulgurite pseudo-color. FIG. b shows the scene in the medium isotherm mode within 29~39°C represented by fulgurite pseudo-color.

Isothermal color: isothermal pseudo-color can be selected by isothermal pseudo-color belt selection command. Currently, 10 isothermal pseudo-colors including white hot, fulgurite, iron red, hot iron, medical treatment, arctic, rainbow 1, rainbow 2, trace red and black hot are supported by default.

Isothermal polarity: when the isotherm function is switch on, setting the polarity pseudo-color on the page invalid, but the black/white polarity of the isotherm can be changed by sending black and white pseudo-color modes.

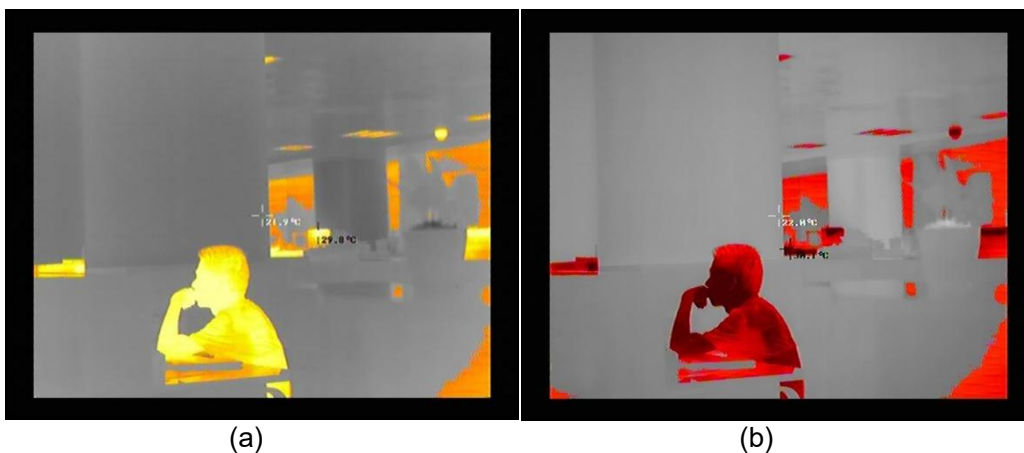


Figure 4-23 Isotherm polarity switching

Taking thermography type as an example, the upper limit threshold is 39.0°C, the lower limit threshold is 29.0°C, and FIG. a shows the white-hot Fulgurite isotherm. FIG.b shows the black-hot Fulgurite isotherm.

4.2.5 Thermography

On the parameters setting interface, the parameters related to temperature measurement is mainly configured, including distance, emissivity, temperature measurement range, temperature show and temperature correction settings., etc.

4.2.5.1 parameter setting

Click the "parameter setting" interface, as shown in Figure 4-24.

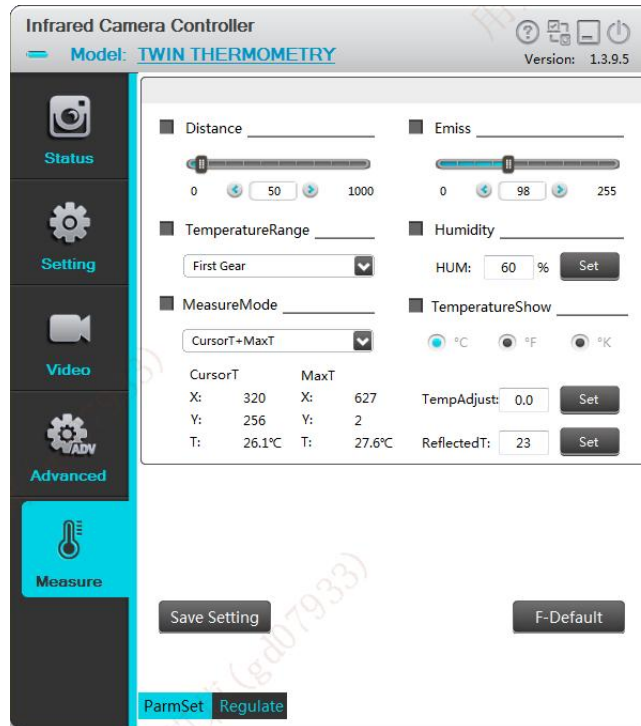
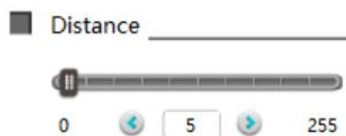


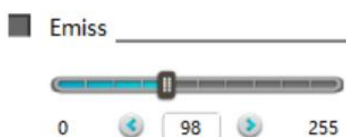
Figure 4-24 Thermography interface

Thermography interface mainly includes distance, emissivity, temperature measurement range, humidity, restore factory value, and save Settings.

Distance : Customizable is available, the typical distance is 5M.



Emissivity: customizable from 0 to 100, typical radiation rate is 98 (effective value is 0.98)



Humidity: customizable from 0~100%, the typical data is 80%.

■ Humidity _____

HUM: %

Temperature Show: the degree Celsius.

■ TemperatureShow _____

°C °F °K

5 Frequently asked questions (FAQ)


5.1 Prepare for demonstration



5.2 Frequently asked questions.

Q1:How to choose the correct serial number to connect?

Answer: After successful software installation, enable the device manager of the computer, and double-click "Port" to display the serial number to be connected by the module,

 Silicon Labs CP210x USB to UART Bridge (COM3) . Select the appropriate serial number from the connection interface for use in connection. The typical connection baud rate is 115200.

| | | | |
|--------|--|----------|--|
| ComNum | <input type="text" value="COM3"/> | Baudrate | <input type="text" value="115200"/> |
| | <ul style="list-style-type: none">COM1COM2COM3COM4 | | <ul style="list-style-type: none">96001920038400115200 |

Q2: The ICC host can't work properly after installing the software and drive.

Answer:

A. Use the device manager to check whether the device drive is abnormal (usually a yellow exclamation point "!").

B. Check the expansion board model, and select the corresponding serial driver according to the expansion board model for installation. The serial port drivers corresponding to the different expansion boards are shown in the table below.

| expansion board model | driver file name | remarks |
|-----------------------|--|---------|
| usb3.0 | the usb3.0 driver installation package | |
| usb2.0 | the usb2.0 driver installation package | |
| VPC | the cp2102 driver | |

Q3: The icc can be connected normally, but the hardware device cannot be turned on.

Answer: The customer needs to check if the computer has a built-in camera and if available, it needs to disable.

Q4: The data changes greatly and the temperature measurement is not accurate when the shutter is opened.

Answer: Temperature is a slowly varying physical quantity, and temperature is not measured too frequently. And you need to drop the abnormal frame when opening the shutter. Shutter status can be obtained by uploading the module message (excluding the frame header, the 27th word) [here one word is 2 bytes].

Q5: How to use digital port format?

Answer:

A. There are two kinds of digital video format can be chosen, CMOS or USB2.0

■ Digital Type _____
 Off CMOS USB2.0

B. If you select the CMOS format, you need to select additional CMOS content and CMOS interface type to use normally.

■ CMOS Content _____ ■ CMOS Interface _____

| | |
|------------------|------------|
| YUV422 | CMOS16 |
| YUV422 | CMOS16 |
| YUV422+param | CMOS8(MSB) |
| Y16 | CMOS8(LSB) |
| Y16+param | |
| Y16+YUV422 | |
| Y16+param+YUV422 | |

Q6: How to obtain the usb2.0 data under the linux system?

Answer: customers need to configure the libusb in their own system.

Q7: Why can't I get an image using the demo in the SDK?

Answer: Please use the icc upper computer to view the cmos content, and align with the SDK Demo settings.

Q8: How does the Non-refrigeration module obtain the temperature of all the points?

Answer: Use SDK to obtain the grayscale data, and then call the formula interface packaged in SDK to convert the grayscale into temperature (CMOS content setting needs parameter mode, such as Y16 parameter line, Y16 parameter line YUV, etc.).

5.3 Emissivity of common materials

| Material | Emissivity | Material | Emissivity |
|------------------------------------|------------|--------------------------|------------|
| Brass mirror | 0.03 | Bright paint(All colour) | 0.90 |
| Polished aluminum or aluminum foil | 0.09 | Stone | 0.92 |
| Pebble | 0.28~0.04 | Concrete | 0.94 |
| Gold-plated copper | 0.30 | Dark paint | 0.95 |
| Solder coated copper | 0.35 | Water | 0.95~0.96 |
| Wood | 0.78 | Smooth black paint | 0.96~0.98 |
| Paper | 0.80~0.95 | Bark | 0.98 |
| Bitumen | 0.85 | Ice | 0.98 |
| Sheet metal | 0.88~0.90 | Skin | 0.98 |

6 Specification of Serial Communication Protocol

6.1 Overview

This chapter describes the applicable scope and format of serial protocol of TWIN module.

1. Serial port (typical baud rate of 115200) is applied to realize the control and communication of host computer of IR module.
2. Detailed protocol contents are defined.
3. The format of basic frame is as shown in Table 6-1.

Table 6-1 Serial port data format

| | | | | |
|-----------------|---|---|----------|--------------------|
| Frame header | | To start the communication frame, two bytes, specified data [55] [AA]. | | |
| Data length | | Total number of bytes (including command word and data) of all command segments of the whole command frame, one byte; | | |
| Command segment | Functional classification | Attribute of current menu. | | |
| | Page | Page number of the current menu attribute. | | |
| | Option | Option in current page, one byte; the highest order bit is used for marking the read-write. | | |
| | | bit[7] | bit[6:0] | Function |
| | | 1(RD) | 80 | Query current page |
| | | | xx | Read a register |
| 0(WR) | xx | Write a register | | |
| Command word | Value of the register, four bytes (32 bits) | | | |
| XOR checkout | | The XOR checkout words of data length byte and all bytes of command segments; | | |
| Frame end | | To end the communication frame, one byte, specified data [F0] | | |

6.2 Module connection protocol

If the software is started for the first time, select the COM port and baud rate and click CONNECT connection. The host sends a connection command, and the slave gives a response to the received query command after receiving the connection command. After receiving the response command, the host analyzes and displays the connection.

The working process as shown in Fig. 6-1.

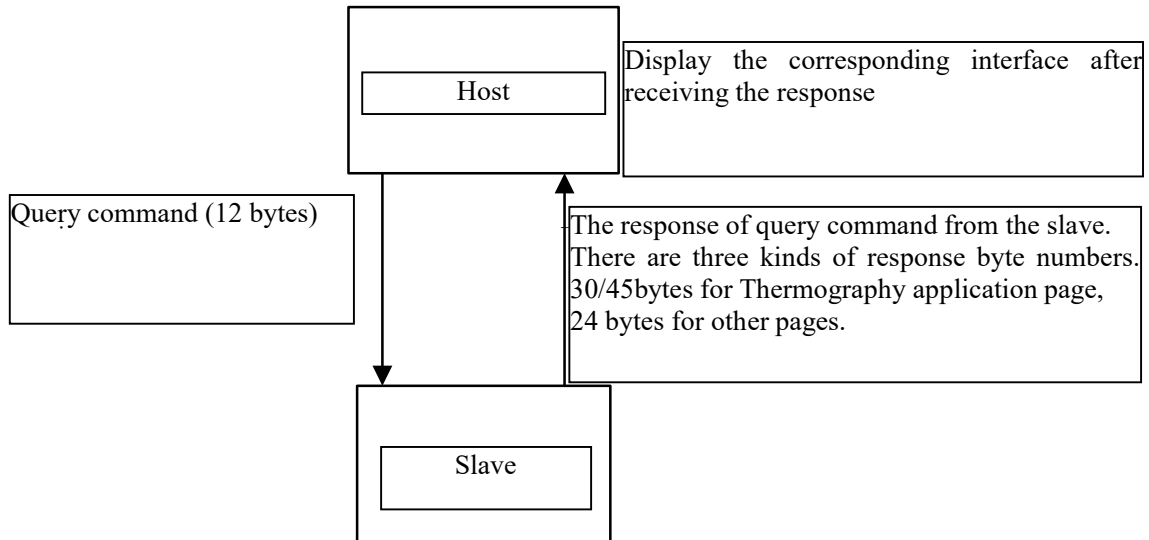


Fig. 6-1 The working process

6.2.1 Downlink protocol

There is only one type of command format of host computer, as shown in Table 5-2.

Table. 6-2 type of command format of host computer

| Frame header | Length | Effective command words | | | | Check bit | Frame end |
|--------------|--------|-------------------------|--------|--------|--------------|-----------|-----------|
| | | Functional category | Page | Option | Command word | | |
| 2 bytes | 1 byte | 1 byte | 1 byte | 1 byte | 4 bytes | 1 byte | 1 byte |
| 00-01 | 02 | 03 | 04 | 05 | 06~09 | 0A | 0B |
| 55 AA | 07 | 00 | 00 | 0x/8x | 00 | XX | F0 |

The option part has 1 byte and the highest bit is used to identify the read-write operation.

The highest bit 1 represents read operation of host computer;

The highest bit 0 represents write operation of host computer;

The option of individual register begins with 0x01.

eg:

Query command: 55 AA + 07 + 00 + 00 + 80 + xxxxxxxx + XX + F0

It is used to inquire the register status of option 1 on the page 00 with function 00, in which, the command word part is invalid and any fixed value can be used.

The format of return command is same as that of query command. Place the query result 0x01020304 in the command word part, such as:

Query feedback command: 55 AA + 13+ 00 + 00 + xx..... + XX + F0

Write operation command: 55 AA + 07 + 00 + 00 + 01 + 01020304 + XX + F0

It is used to write 0x01020304 into the register of option 1 on the page 00 with function 00.

6.2.1.1 Control command

The control command format is as shown in Table 6-3.

Table 6-3 Control command format

| Command word | Byte | Parameter description | Parameter type |
|--------------|------------|------------------------------|---------------------------|
| Byte0 | 0x55 | Frame header byte 1 | Frame header |
| Byte1 | 0xAA | Frame header byte 2 | |
| Byte2 | 0x07 | The length is 7 | Command length |
| Byte3 | 0x00 | Status page | Functional classification |
| | 0x01 | Setup page | |
| | 0x02 | Video page | |
| | 0x03 | Application page | |
| | 0x04 | Temperature measurement page | |
| | 0xA0 | / | |
| Byte4 | 0x00 | Page 1 | Page |
| | 0x01 | Page 2 | |
| | 0x02 | Page 3 | |
| Byte5 | 0x01~0x07F | Option | ID number of command word |
| Byte6 | 0x00 | Command high [31:24] | Command word |
| Byte7 | 0x00 | Command low [23:16] | |
| Byte8 | 0x00 | Command low [15:8] | |
| Byte9 | 0x00 | Command low [7:0] | |
| Byte10 | 0xFF | XOR checkout | |
| Byte11 | 0xF0 | Frame end | Frame end |

6.2.1.1.1 Setup page

All operation commands of the function setting page: (55 AA 07 01 00 + option + command word (4 bytes) + XOR +F0). The command contents are specified as in Table 6-4.

Table 6-4 Operation commands of setup page

| Option content | Option | Command word | Operation content | Operation command |
|-----------------------------------|--------|--------------|--------------------------|--------------------------------------|
| Automatic compensation time (min) | 0x01 | 00 00 00 xx | 0~100 | 55 AA 07 01 00 01 00 00 00 xx XOR F0 |
| Image freezing | 0x02 | 00 0000 00 | Not freezing | 55 AA 07 01 00 02 00 00 00 00 04 F0 |
| | | 00 0000 01 | Freezing | 55 AA 07 01 00 02 00 00 00 01 05 F0 |
| Test Screen Switching | 0x03 | 00 00 00 00 | Real image | 55 AA 07 01 00 03 00 00 00 00 05 F0 |
| | | 00 00 00 01 | Chess pattern | 55 AA 07 01 00 03 00 00 00 01 04 F0 |
| | | 00 00 00 02 | Row gradients pattern | 55 AA 07 01 00 03 00 00 00 02 07 F0 |
| | | 00 00 00 03 | Column gradients pattern | 55 AA 07 01 00 03 00 00 00 03 06 F0 |
| Save settings | 0x04 | 00 00 00 01 | Setting | 55 AA 07 01 00 04 00 00 00 01 03 F0 |
| Restore to factory default | 0x05 | 00 00 00 01 | Setting | 55 AA 07 01 00 05 00 00 00 01 02 F0 |
| Module restart | 0x06 | / | / | Not supported |
| temperature calibration | 0x07 | 00 00 00 00 | off | 55 AA 07 01 00 07 00 00 00 00 01 F0 |
| | | 00 00 00 01 | on | 55 AA 07 01 00 07 00 00 00 01 00 F0 |
| Shutter control option | 0x08 | / | / | Not supported |
| Shutter manual control command | 0x08 | 00 00 00 00 | Shutter close | 55 AA 07 A0 02 08 00 00 00 00 AD F0 |
| | | 00 00 00 01 | Shutter open | 55 AA 07 A0 02 08 00 00 00 01 AC F0 |
| Gain control (Observation type) | 0x09 | 00 00 00 00 | Standard | 55 AA 07 01 00 09 00 00 00 00 0F F0 |
| | | 00 00 00 01 | Low noise | 55 AA 07 01 00 09 00 00 00 01 0E F0 |

Note:

Timing compensation operation content 0 means timing compensation function is off, 1~100 means 1min~100min.

6.2.1.1.2 Video page

(1) Analog Video page

All operation command formats of the analog video page: (55 AA 07 02 00 + option + command word (4 byte) + XOR + F0). See Table 6-5 for details.

Table 6-5 Operation commands of analog video page

| Option content | Option | Command word | Operation content | Operation command |
|--|--------|--------------|--|--------------------------------------|
| Analog video switch | 0x01 | 00 00 00 00 | Off | 55 AA 07 02 00 01 00 00 00 00 04 F0 |
| | | 00 00 00 01 | On | 55 AA 07 02 00 01 00 00 00 01 05 F0 |
| Video system switching | 0x02 | 00 00 00 00 | P:768x576 | / (This function is not supported) |
| | | 00 00 00 01 | N:640x480 | / (This function is not supported) |
| | | 00 00 00 02 | P:720x576 | 55 AA 07 02 00 02 00 00 00 02 05 F0 |
| | | 00 00 00 03 | N:720x480 | 55 AA 07 02 00 02 00 00 00 03 04 F0 |
| Frame rate setting P-system : 50/25/9 N-system : 60/30/9 | 0x03 | 00 00 00 00 | 50/60Hz | 55 AA 07 02 00 03 00 00 00 00 06 F0 |
| | | 00 00 00 01 | 25/30Hz | 55 AA 07 02 00 03 00 00 00 01 07 F0 |
| | | 00 00 00 02 | 9Hz | 55 AA 07 02 00 03 00 00 00 02 04 F0 |
| Pseudo-color | 0x04 | 00 00 00 00 | White hot | 55 AA 07 02 00 04 00 00 00 00 XOR F0 |
| | | 00 00 00 01 | Fulgurite | 55 AA 07 02 00 04 00 00 00 01 XOR F0 |
| | | 00 00 00 02 | Iron Red | 55 AA 07 02 00 04 00 00 00 02 XOR F0 |
| | | 00 00 00 03 | Hot Iron | 55 AA 07 02 00 04 00 00 00 03 XOR F0 |
| | | 00 00 00 04 | Medical | 55 AA 07 02 00 04 00 00 00 04 XOR F0 |
| | | 00 00 00 05 | Arctic | 55 AA 07 02 00 04 00 00 00 05 XOR F0 |
| | | 00 00 00 06 | Rainbow 1 | 55 AA 07 02 00 04 00 00 00 06 XOR F0 |
| | | 00 00 00 07 | Rainbow 2 | 55 AA 07 02 00 04 00 00 00 07 XOR F0 |
| | | 00 00 00 08 | Tint | 55 AA 07 02 00 04 00 00 00 08 XOR F0 |
| | | 00 00 00 09 | Black hot | 55 AA 07 02 00 04 00 00 00 09 XOR F0 |
| Mirror image | 0x05 | 00 00 00 00 | N/A | 55 AA 07 02 00 05 00 00 00 00 00 F0 |
| | | 00 00 00 01 | Mirror X | 55 AA 07 02 00 05 00 00 00 01 01 F0 |
| | | 00 00 00 02 | Mirror Y | 55 AA 07 02 00 05 00 00 00 02 02 F0 |
| | | 00 00 00 03 | Mirror XY | 55 AA 07 02 00 05 00 00 00 03 03 F0 |
| EZOOM | 0x06 | 00 00 00 xx | 8~64(the effective value range 1 to 8) | 55 AA 07 02 00 06 00 00 00 xx XOR F0 |
| Coordinate X of | 0x07 | 00 00 | 0~width-1 | 55 AA 07 02 00 07 00 00 xx xx XOR F0 |

| Option content | Option | Command word | Operation content | Operation command |
|---|--------|--------------------|-------------------|--------------------------------------|
| the center of zoomed area | | xxxx(MSB) | | |
| Coordinate Y of the center of zoomed area | 0x08 | 00 00 xxxx(MSB) | 0~height-1 | 55 AA 07 02 00 08 00 00 xx xx XOR F0 |
| Hotspot track switch | 0x09 | / | / | This page is not supported |

Note:

EZOOM magnification of the operation content N need to be a multiple of 8, the actual effective value is N/8 times.

(2) Digital Video page

All operation command formats of the digital video page: (55 AA 07 02 01 + option + command word (4 byte) + XOR + F0) See Table 6-6 for details.

Table 6-6 Operation commands of digital video page

| Option content | Option | Command word | Operation content | Operation command |
|---------------------------------|--------|--------------|------------------------------|-------------------------------------|
| External synchronization switch | 0x01 | 00 00 00 00 | Slave mode-Off | 55 AA 07 02 01 01 00 00 00 00 05 F0 |
| | | 00 00 00 01 | Slave mode-On | 55 AA 07 02 01 01 00 00 00 01 04 F0 |
| | | 00 00 00 02 | Master mode | 55 AA 07 02 01 01 00 00 00 02 07 F0 |
| Digital port type | 0x02 | 00 00 00 00 | Off | 55 AA 07 02 01 02 00 00 00 00 06 F0 |
| | | 00 00 00 01 | USB2.0 | 55 AA 07 02 01 02 00 00 00 01 07 F0 |
| | | 00 00 00 02 | CMOS | 55 AA 07 02 01 02 00 00 00 02 04 F0 |
| CMOS content selection | 0x03 | 00 00 00 00 | YUV422 | 55 AA 07 02 01 03 00 00 00 00 07 F0 |
| | | 00 00 00 01 | YUV422_ parameter line | 55 AA 07 02 01 03 00 00 00 01 06 F0 |
| | | 00 00 00 02 | YUV16 | 55 AA 07 02 01 03 00 00 00 02 05 F0 |
| | | 00 00 00 03 | YUV16_ parameter line | 55 AA 07 02 01 03 00 00 00 03 04 F0 |
| | | 00 00 00 04 | Y16_YUV422 | 55 AA 07 02 01 03 00 00 00 04 03 F0 |
| | | 00 00 00 05 | Y16_parameter line_YUV422 | 55 AA 07 02 01 03 00 00 00 05 02 F0 |

| Option content | Option | Command word | Operation content | Operation command |
|--|--------|--------------|-----------------------|-------------------------------------|
| CMOS interface type | 0x04 | 00 00 00 00 | CMOS16 | 55 AA 07 02 01 04 00 00 00 00 00 F0 |
| | | 00 00 00 01 | CMOS8 (MSB first) | 55 AA 07 02 01 04 00 00 00 01 01 F0 |
| | | 00 00 00 02 | CMOS8 (LSB first) | 55 AA 07 02 01 04 00 00 00 02 02 F0 |
| Frame rate setting P-system 50/25/9 N-system 60/30/9 | 0x05 | 00 00 00 00 | 50/60Hz | 55 AA 07 02 01 05 00 00 00 00 01 F0 |
| | | 00 00 00 01 | 25/30Hz | 55 AA 07 02 01 05 00 00 00 01 00 F0 |
| | | 00 00 00 02 | 9Hz | 55 AA 07 02 01 05 00 00 00 02 03 F0 |
| LVDS switch | 0x06 | 00 00 00 00 | Off | 55 AA 07 02 01 06 00 00 00 00 02 F0 |
| | | 00 00 00 01 | On | 55 AA 07 02 01 06 00 00 00 01 03 F0 |
| Scene compensation | 0x07 | 00 00 00 01 | Compensation | 55 AA 07 02 01 07 00 00 00 01 02 F0 |
| Shutter compensation | 0x08 | 00 00 00 01 | Compensation | 55 AA 07 02 01 08 00 00 00 01 0D F0 |
| Digital port output clock phase | 0x09 | 00 00 00 00 | Rising edge alignment | 55 AA 07 02 01 09 00 00 00 00 0D F0 |
| | | 00 00 00 01 | Fall edge alignment | 55 AA 07 02 01 09 00 00 00 01 0C F0 |

(3) Algorithm setting page

All operation command formats of the algorithm setting page:

(55 AA 07 02 02 + option + command word (4 byte) + XOR+ F0).

See Table 6-7 for details.

Table 6-7 Operation commands of algorithm setting page

| Option content | Option | Command word | Operation content | Operation command |
|----------------------------------|--------|--------------|-------------------|--------------------------------------|
| Anti striation switch | 0x05 | 00 00 00 00 | Off | 55 AA 07 02 02 05 00 00 00 00 02 F0 |
| | | 00 00 00 01 | On | 55 AA 07 02 02 05 00 00 00 01 03 F0 |
| Image mode(sharpening intensity) | 0x06 | 00 00 00 00 | Soft mode | 55 AA 07 02 02 06 00 00 00 00 01 F0 |
| | | 00 00 00 01 | Standard mode | 55 AA 07 02 02 06 00 00 00 01 00 F0 |
| | | 00 00 00 02 | Enhancement mode | 55 AA 07 02 02 06 00 00 00 02 03 F0 |
| Brightness | 0x0a | 00 00 00 xx | 0~16 | 55 AA 07 02 02 0a 00 00 00 xx XOR F0 |

| Option content | Option | Command word | Operation content | Operation command |
|------------------------|--------|--------------|------------------------------|---|
| Contrast | 0x0b | 00 00 00 xx | 0~255 | 55 AA 07 02 02 02 0b 00 00 00 xx XOR F0 |
| Enhanced detail gain | 0x12 | 00 00 00 xx | 0~255 | 55 AA 07 02 02 02 12 00 00 00 xx XOR F0 |
| Dimming mode | 0x18 | 00 00 00 00 | 0 | 55 AA 07 02 02 02 18 00 00 00 00 1F F0 |
| | | 00 00 00 01 | 1 | 55 AA 07 02 02 02 18 00 00 00 01 1E F0 |
| | | 00 00 00 02 | 2 | 55 AA 07 02 02 02 18 00 00 00 02 1D F0 |
| Image hue | 0x19 | 00 00 00 00 | warm | 55 AA 07 02 02 02 19 00 00 00 00 1E F0 |
| | | 00 00 00 01 | cool | 55 AA 07 02 02 02 19 00 00 00 01 1F F0 |
| Image observation mode | 0x20 | 00 00 00 00 | Observation mode | 55 AA 07 02 02 02 20 00 00 00 00 26 F0 |
| | | 00 00 00 01 | Temperature measurement mode | 55 AA 07 02 02 02 20 00 00 00 01 27 F0 |

6. 2. 1. 1. 3 Advanced application page

1) Focusing page

Unavailable for the module.

2) Defective pixel page

All operation command formats of the defective pixel page: (55 AA 07 03 01 + option + command word (4 byte) + XOR + F0). See Table 6-8 for details.

Table 6-8 Operation commands of defective pixel page

| Option content | Option | Command word | Operation content | Operation command |
|--------------------------|--------|--------------|--------------------------|--------------------------------------|
| Cursor coordinate X | 0x02 | 00 00 xxxx | 0~width-1 | 55 AA 07 03 01 02 00 00 xx xx XOR F0 |
| Cursor coordinate Y | 0x03 | 00 00 xxxx | 0~height-1 | 55 AA 07 03 01 03 00 00 xx xx XOR F0 |
| Defective pixel addition | 0x04 | 00 00 00 01 | Defective pixel addition | 55 AA 07 03 01 04 00 00 00 01 00 F0 |
| | | 00 00 00 03 | Defective column | 55 AA 07 03 01 04 00 00 00 02 03 F0 |

| | | | | |
|------------------------|------|-------------|----------|-------------------------------------|
| | | | addition | |
| Defective pixel saving | 0x05 | 00 00 00 01 | Setting | 55 AA 07 03 01 05 00 00 00 01 01 F0 |

3) Menu function page

Unavailable for the module.

4) Hots tracking page 1 (region analysis)

All operation command formats of the menu page: (55 AA 07 03 03 + option + command word (4 byte) + XOR+ F0). See Table 6-9 for details.

Table 6-9 Operation commands of menu function page

| Option content | Option | Command word | Operation content | Operation command |
|---------------------------------------|--------|--------------|-------------------------|--------------------------------------|
| Anaysis Mode | 0x01 | 00 00 00 00 | Anaysis Off | 55 AA 07 03 03 01 00 00 00 00 06 F0 |
| | | 00 00 00 01 | Full screen anaysis | 55 AA 07 03 03 01 00 00 00 01 07 F0 |
| | | 00 00 00 02 | Region 1 | 55 AA 07 03 03 01 00 00 00 02 04 F0 |
| | | 00 00 00 03 | Region 2 | 55 AA 07 03 03 01 00 00 00 03 05 F0 |
| | | 00 00 00 04 | Region 3 | 55 AA 07 03 03 01 00 00 00 04 02 F0 |
| Region upper left corner coordinate X | 0x02 | 00 00 xx xx | Region analysis (0~639) | 55 AA 07 03 03 02 00 00 xx xx XOR F0 |
| Region upper left corner coordinate Y | 0x03 | 00 00 xx xx | Region analysis (0~511) | 55 AA 07 03 03 03 00 00 xx xx XOR F0 |
| Region width W | 0x04 | 00 00 xx xx | Region analysis 1~640 | 55 AA 07 03 03 04 00 00 xx xx XOR F0 |
| Region height H | 0x05 | 00 00 xx xx | Region analysis 1~512 | 55 AA 07 03 03 05 00 00 xx xx XOR F0 |

Note:

① Observation type setting range 0 to 65535, Thermography type setting range -50.0°C to 1000.0°C, magnify 10 times transmission.

5) Hotspot tracking page 3

Pseudo-color vision enhancement all operation commands: 55 AA 07 03 05 + option + command word (4 byte) +XOR + F0.

Fig.6-10 isotherm operation commands

| Option content | Option | Command word | Operation content | Operation command |
|--|--------|--------------|-------------------|--------------------------------------|
| Isotherm switch (isotherm) | 0x06 | 00 00 00 00 | Off | 55 AA 07 03 05 06 00 00 00 00 07 F0 |
| | | 00 00 00 01 | On | 55 AA 07 03 05 06 00 00 00 01 06 F0 |
| Upper limit of isotherm threshold | 0x08 | 00 00 xx xx | Note① | 55 AA 07 03 05 08 00 00 xx xx XOR F0 |
| Lower limit of isotherm threshold | 0x09 | 00 00 xx xx | | 55 AA 07 03 05 09 00 00 xx xx XOR F0 |
| Isothermal pseudo-color band selection | 0x0d | 00 00 00 00 | White heat | 55 AA 07 03 05 0d 00 00 00 00 0C F0 |
| | | 00 00 00 01 | fulgurite | 55 AA 07 03 05 0d 00 00 00 01 0D F0 |
| | | 00 00 00 02 | iron red | 55 AA 07 03 05 0d 00 00 00 02 0E F0 |
| | | 00 00 00 03 | hot iron | 55 AA 07 03 05 0d 00 00 00 03 0F F0 |
| | | 00 00 00 04 | medical treatment | 55 AA 07 03 05 0d 00 00 00 04 08 F0 |
| | | 00 00 00 05 | arctic | 55 AA 07 03 05 0d 00 00 00 05 09 F0 |
| | | 00 00 00 06 | Rainbow 1 | 55 AA 07 03 05 0d 00 00 00 06 0A F0 |
| | | 00 00 00 07 | Rainbow 2 | 55 AA 07 03 05 0d 00 00 00 07 0B F0 |
| | | 00 00 00 08 | Trace red | 55 AA 07 03 05 0d 00 00 00 08 04 F0 |
| | | 00 00 00 09 | Black heat | 55 AA 07 03 05 0d 00 00 00 09 05 F0 |

Note:①Thermography type setting range -50.0℃ to 1000.0℃, magnify 10 times transmission.

6. 2. 1. 1. 4 Temperature measurement page

1) Parameter setting page

All operation commands of the function parameter setting page : (55 AA 07 04 00 + option + command word (4 bytes) + XOR + F0) . The command contents are specified as shown in Table6-11.

Table 6-11 Operation commands of menu function page

| Option content | Option | Command word | Operation content | Operation command |
|-------------------------------|--------|--------------|-------------------------|--------------------------------------|
| Distance setting | 0x01 | 00 00 00 xx | 0~100 | 55 AA 07 04 00 01 00 00 00 xx XOR F0 |
| Emissivity setting | 0x02 | 00 00 00 xx | 0~100 | 55 AA 07 04 00 02 00 00 00 xx XOR F0 |
| Measurement mode | 0x03 | 00 00 00 00 | Min + max temp. | 55 AA 07 04 00 03 00 00 00 00 00 F0 |
| | | 00 00 00 01 | cursor spot+ max temp. | 55 AA 07 04 00 03 00 00 00 01 01 F0 |
| | | 00 00 00 02 | min + cursor spot temp. | 55 AA 07 04 00 03 00 00 00 02 02 F0 |
| Factory reset | 0x06 | 00 00 00 01 | Setting | 55 AA 07 04 00 06 00 00 00 01 04 F0 |
| Reflected setting | 0x07 | 00 00 xx xx | Setting | 55 AA 07 04 00 07 00 00 xx xx XOR F0 |
| Save settings | 0x04 | 00 00 00 01 | Setting | 55 AA 07 01 00 04 00 00 00 01 03 F0 |
| Humidity Save settings | 0x08 | 00 00 00 xx | Setting | 55 AA 07 04 00 08 00 00 00 xx XOR F0 |
| Temperature measurement range | 0x09 | 00 00 00 00 | -20°C~150°C | 55 AA 07 04 00 09 00 00 00 00 0A F0 |
| | | 00 00 00 01 | -20°C~550°C | 55 AA 07 04 00 09 00 00 00 01 0B F0 |

2) Thermography calibration page

All operation commands of the function blackbody correction page: (55 AA 07 04 01 + option + command word (4 bytes) + XOR + F0) . See Table 6-12 for details.

Table6-12 Blackbody correction page operating command

| Option content | Option | Command word | Operation content | Operation command |
|---------------------------------------|--------|--------------|--------------------------------------|--------------------------------------|
| Low temperature blackbody collection | 0x01 | 00 00 00 01 | Collect low temperature Y16 | 55 AA 07 04 01 01 00 00 00 01 02 F0 |
| High temperature blackbody collection | 0x02 | 00 00 00 01 | Collect high temperature Y16 | 55 AA 07 04 02 02 00 00 00 01 01 F0 |
| Two point collection | 0x03 | 00 00 00 01 | Start correction | 55 AA 07 04 01 03 00 00 00 01 00 F0 |
| Single point blackbody acquisition | 0x04 | 00 00 xx xx | 0~8000, corresponding to 0 °C ~800°C | 55 AA 07 04 01 04 00 00 00 xx XOR F0 |
| Single point collection | 0x05 | 00 00 00 01 | Start correction | 55 AA 07 04 01 05 00 00 00 01 06 F0 |

| | | | | |
|--|------|----------------|---|--------------------------------------|
| Save options | 0x04 | 00 00 00 01 | Setting | 55 AA 07 01 00 04 00 00 00 01 03 F0 |
| Low temperature blackbody setting | 0x06 | 00 00 XX XX | -400~8000, corresponding to -40 °C ~800°C | 55 AA 07 04 01 06 00 00 xx xx XOR F0 |
| High temperature blackbody setting temperature switch | 0x07 | 00 00 XX XX | | 55 AA 07 04 01 07 00 00 xx xx XOR F0 |
| Single point blackbody setting | 0x08 | 00 00 xxxx | | 55 AA 07 04 01 08 00 00 xx xx XOR F0 |
| Cancel setting | 0x09 | 00 00 00 01 | | 55 AA 07 04 01 09 00 00 00 01 0A F0 |

6.2.1.2 Query command

The query commands are as shown in Table 6-13.

Table 6-13 Query commands

| Command word | Byte | Parameter description | Parameter type |
|--------------|------|-----------------------|--|
| Byte0 | 0x55 | Frame header byte 1 | Frame header |
| Byte1 | 0xAA | Frame header byte 2 | |
| Byte2 | 0x07 | Length is 7 | Command length |
| Byte3 | 0x00 | Status page | Functional classification |
| | 0x01 | Setup page | |
| | 0x02 | Video page | |
| | 0x03 | Application page | |
| | 0x04 | Measurement page | |
| Byte4 | 0x00 | Page 1 | Page |
| | 0x01 | Page 2 | |
| | 0x02 | Page 3 | |
| Byte5 | 0x80 | Page query code | |
| Byte6 | 0x00 | 0x00 | Command word (command word is invalid at query, and the default is 0x00) |
| Byte7 | 0x00 | 0x00 | |
| Byte8 | 0x00 | 0x00 | |
| Byte9 | 0x00 | 0x00 | |
| Byte10 | 0xXX | XOR checkout | Check bit |

| | | | |
|--------|------|-----------|-----------|
| Byte11 | 0xF0 | Frame end | Frame end |
|--------|------|-----------|-----------|

6.2.2 Uplink protocol

6.2.2.1 Handshake return

If the slave computer requires a certain time in responding to the control of host computer, the slave computer will return the operation completion command upon its completion of response operation, so that the host computer can continue operation. If no return command is received within the agreed time, the prompt of operation failed will be displayed.

The return command format is as shown in Table 6-14.

Table 6-14 Return command format

| Frame header | Length | Option | Checksum | Frame end |
|--------------|--------|--------|----------|-----------|
| 2 bytes | 1 byte | 1 byte | 1 byte | 1 byte |
| 00-01 | 02 | 03 | 04 | 05 |
| 55 AA | 01 | xx | XX | F0 |

1. Confirm the command receiving: 55 AA 01 00 01 F0.
2. Receiving error, resending of command is requested: 55 AA 01 01 00 F0.

See Table 6-15 for details of return command.

Table 6-15 Return commands

| Command word | Byte | Parameter description | Parameter type |
|--------------|--------|--|---|
| Byte0 | 0x55 | Frame header byte 1 | Frame header |
| Byte1 | 0xAA | Frame header byte 2 | |
| Byte2 | 0x01 | Length is 1 | Command length |
| Byte3 | 0x00 | Receiving confirmation | Receiving confirmation |
| | 0x01 | Receiving error, resending of command is requested | Receiving error, resending of command is requested |
| | 0x02 | Save settings | Return to current option number upon the completion of response |
| | 0x03 | Restore factory settings | |
| | 0x04 | Restart | |
| | 0x05 | Scene compensation | |
| | 0x06 | Shutter compensation | |
| | 0x13 | BL compensation | |
| | 0x14 | BH compensation | |
| | 0x15 | Calculate K | |
| | 0x16 | Save K | |
| 0x17 | Load K | | |

| Command word | Byte | Parameter description | Parameter type |
|--------------|-------------|--|---|
| | 0x18 | Load initial K | |
| | 0x25 | Upload BL | |
| | 0x26 | Upload BH | |
| | 0x28 | Upload NUC | |
| | 0x29 | Temperature parameter restored to factory default successfully | |
| | 0x1A | Upload B0 | |
| | 0x1B | Upload B1 | |
| | 0x1C | Upload B2 | |
| | 0x1D | Upload B3 | |
| | 0x1E | Upload B4 | |
| Byte3 | 0x1F | Upload B5 | Return to current option number upon the completion of response |
| | 0x20 | Upload B6 | |
| | 0x21 | Upload B7 | |
| | 0x22 | Upload B8 | |
| | 0x23 | Upload B9 | |
| | 0x24 | Upload K | |
| | 0x25 | Upload BL | |
| | 0x26 | Upload BH | |
| | 0x27 | Upload NUC | |
| | 0x50 | Upload PROGRAM | |
| | 0x51 | Upload FILTER | |
| | 0x52 | Upload RMS | |
| | 0x53 | Upload IDE | |
| | 0x54 | Upload IMAGE_RGB | |
| | 0x55 | Upload SINGLE_TMP | |
| | 0x56 | Upload START_IMAGE_RGB | |
| | 0x57 | Upload START_IMAGE | |
| | 0x58 | Upload MENU_RGB | |
| 0x59 | Upload MENU | | |

| Command word | Byte | Parameter description | Parameter type |
|--------------|------|---|---|
| | 0x5A | Upload LOG | |
| | 0x5B | Upload HF_CURSOR | |
| | 0x5C | Upload ZSP_PROGRAM | |
| | 0x34 | Program upgrading | |
| | 0x39 | Defective pixel saving | |
| | 0x40 | Defective pixel addition | |
| | 0x47 | Low temperature blackbody collection completed | |
| | 0x41 | High temperature blackbody collection completed | |
| | 0x42 | Two point calibration successful | |
| | 0x43 | Two point calibration failed | |
| Byte3 | 0x44 | Single point collection completed | Return to current option number upon the completion of response |
| | 0x45 | Single point calibration successful | |
| | 0x46 | Single point calibration failed | |
| | 0xA0 | The "start to upload" mark of asic | |
| | 0xA1 | The "upgrading failed" mark of asic | |
| | 0xA2 | asic starts to flash | |
| Byte4 | 0xXX | XOR checkout | Check bit |
| Byte5 | 0xF0 | Frame end | Frame end |

6.2.2.2 Query return

After receiving the query command, the slave computer will respond and return all information of the queried page to the host computer. The response command format of lower computer is consistent with the return command format at query. Query returns are generally 24 bytes, and the thermography application page has special 30, 45 bytes.

The format of 24\30\45 bytes query return commands are as shown in Table6-16、 6-17、 6-18.

Table 6-16 Format of 24-bytes query return command

| Frame header | Length | Valid command word | | | Check bit | Frame end |
|--------------|--------|---------------------------|-------|--------|-----------|-----------|
| | | Functional classification | Page | Option | | |
| 2Byte | 1Byte | 1Byte | 1Byte | 17Byte | 1Byte | 1Byte |

| | | | | | | | |
|-------|----|----|----|-------|------------|----|----|
| 00-01 | 02 | 03 | 04 | 05~21 | 22 | 23 | |
| 55 | AA | 13 | 00 | 00 | 0000000... | XX | 55 |

Table 6-17 Format of 30-bytes query return command

| Frame header | Length | Valid command word | | | Check bit | Frame end | |
|--------------|--------|---------------------------|-------|--------|-------------|-----------|----|
| | | Functional classification | Page | Option | | | |
| 2Byte | 1Byte | 1Byte | 1Byte | 23Byte | 1Byte | 1Byte | |
| 00-01 | 02 | 03 | 04 | 05~27 | 28 | 29 | |
| 55 | AA | 19 | 00 | 00 | 00 00000... | XX | F0 |

Table 6-18 Format of 45-bytes query return command

| Frame header | Length | Valid command word | | | Frame header | Length | |
|--------------|--------|---------------------------|-------|--------|--------------|--------|----|
| | | Functional classification | Page | Option | | | |
| 2Byte | 1Byte | 1Byte | 1Byte | 38Byte | 1Byte | 1Byte | |
| 00-01 | 02 | 03 | 04 | 05~42 | 43 | 44 | |
| 55 | AA | 28 | 00 | 00 | 00 00000... | XX | F0 |

Details of 24\30\45 bytes query response command of slave computer are described in Table 6-19, 6-20, 6-21.

Table 6-19 24-bytes query return command

| Command word | Byte | Parameter description | Parameter type |
|--------------|------|-----------------------|---------------------------|
| Byte0 | 0x55 | Frame header byte 1 | Frame header |
| Byte1 | 0xAA | Frame header byte 2 | |
| Byte2 | 0x13 | Length is 19 | Command length |
| Byte3 | 0x00 | Status page | Functional classification |
| | 0x01 | Setup page | |
| | 0x02 | Video page | |
| | 0x03 | Advance setting page | |
| | 0x04 | Measurement page | |
| Byte4 | 0x00 | Page 1 | |
| | 0x01 | Page 2 | |
| | 0x01 | Page 3 | |
| Byte5 | 0x00 | Command of option 1 | |
| Byte6 | 0x00 | Command of option 2 | |
| Byte7 | 0x00 | Command of option 3 | |
| Byte8 | 0x00 | Command of option 4 | |
| Byte9 | 0x00 | Command of option 5 | |

| Command word | Byte | Parameter description | Parameter type |
|--------------|------|-----------------------|----------------|
| Byte10 | 0x00 | Command of option 6 | |
| Byte11 | 0x00 | Command of option 7 | |
| Byte12 | 0x00 | Command of option 8 | |
| Byte13 | 0x00 | Command of option 9 | |
| Byte14 | 0x00 | Command of option 10 | |
| Byte15 | 0x00 | Command of option 11 | |
| Byte16 | 0x00 | Command of option 12 | |
| Byte17 | 0x00 | Command of option 13 | |
| Byte18 | 0x00 | Command of option 14 | |
| Byte19 | 0x00 | Command of option 15 | |
| Byte20 | 0x00 | Command of option 16 | |
| Byte21 | 0x00 | Command of option 17 | |
| Byte22 | 0xXX | XOR checkout | |
| Byte23 | 0xF0 | Frame end | Frame end |

Table6-20 30-bytes query return command

| Command word | Byte | Parameter description | Parameter type |
|--------------|------|-----------------------|---------------------------|
| Byte0 | 0x55 | Frame header byte 1 | Frame header |
| Byte1 | 0xAA | Frame header byte 2 | |
| Byte2 | 0x19 | Length is 25 | Command length |
| Byte3 | 0x00 | Status page | Functional classification |
| | 0x01 | Setup page | |
| | 0x02 | Video page | |
| | 0x03 | Advance setting page | |
| | 0x04 | Measurement page | |
| Byte4 | 0x00 | Page 1 | Page |
| | 0x01 | Page 2 | |
| | 0x01 | Page 3 | |
| Byte5 | 0x00 | Command of option 1 | Command word |

| Command word | Byte | Parameter description | Parameter type |
|--------------|------|-----------------------|----------------|
| Byte6 | 0x00 | Command of option 2 | |
| Byte7 | 0x00 | Command of option 3 | |
| Byte8 | 0x00 | Command of option 4 | |
| Byte9 | 0x00 | Command of option 5 | |
| Byte10 | 0x00 | Command of option 6 | |
| Byte11 | 0x00 | Command of option 7 | |
| Byte12 | 0x00 | Command of option 8 | |
| Byte13 | 0x00 | Command of option 9 | |
| Byte14 | 0x00 | Command of option 10 | |
| Byte15 | 0x00 | Command of option 11 | |
| Byte16 | 0x00 | Command of option 12 | |
| Byte17 | 0x00 | Command of option 13 | |
| Byte18 | 0x00 | Command of option 14 | |
| Byte19 | 0x00 | Command of option 15 | |
| Byte20 | 0x00 | Command of option 16 | |
| Byte21 | 0x00 | Command of option 17 | |
| Byte22 | 0x00 | Command of option 18 | |
| Byte23 | 0x00 | Command of option 19 | |
| Byte24 | 0x00 | Command of option 20 | |
| Byte25 | 0x00 | Command of option 21 | |
| Byte26 | 0x00 | Command of option 22 | |
| Byte27 | 0x00 | Command of option 23 | |
| Byte28 | 0xXX | XOR checkout | |
| Byte29 | 0xF0 | Frame end | Frame end |

Table6-21 45-bytes query return command

| Command word | Byte | Parameter description | Parameter type |
|--------------|------|-----------------------|----------------|
| Byte0 | 0x55 | Frame header byte 1 | Frame header |
| Byte1 | 0xAA | Frame header byte 2 | |

| Command word | Byte | Parameter description | Parameter type |
|--------------|------|-----------------------|---------------------------|
| Byte2 | 0x28 | Length is 40 | Command length |
| Byte3 | 0x00 | Status page | Functional classification |
| | 0x01 | Setup page | |
| | 0x02 | Video page | |
| | 0x03 | Advance setting page | |
| | 0x04 | Measurement page | |
| Byte4 | 0x00 | Page 1 | Page |
| | 0x01 | Page 2 | |
| | 0x02 | Page 3 | |
| Byte5 | 0x00 | Command of option 1 | Command word |
| Byte6 | 0x00 | Command of option 2 | |
| Byte7 | 0x00 | Command of option 3 | Command word |
| Byte8 | 0x00 | Command of option 4 | |
| Byte9 | 0x00 | Command of option 5 | |
| Byte10 | 0x00 | Command of option 6 | |
| Byte11 | 0x00 | Command of option 7 | |
| Byte12 | 0x00 | Command of option 8 | |
| Byte13 | 0x00 | Command of option 9 | |
| Byte14 | 0x00 | Command of option 10 | |
| Byte15 | 0x00 | Command of option 11 | |
| Byte16 | 0x00 | Command of option 12 | |
| Byte17 | 0x00 | Command of option 13 | |
| Byte18 | 0x00 | Command of option 14 | |
| Byte19 | 0x00 | Command of option 15 | |
| Byte20 | 0x00 | Command of option 16 | |
| Byte21 | 0x00 | Command of option 17 | |
| Byte22 | 0x00 | Command of option 18 | |
| Byte23 | 0x00 | Command of option 19 | |

| Command word | Byte | Parameter description | Parameter type | |
|--------------|------|-----------------------|----------------|--------------|
| Byte24 | 0x00 | Command of option 20 | | |
| Byte25 | 0x00 | Command of option 21 | | |
| Byte26 | 0x00 | Command of option 22 | | |
| Byte27 | 0x00 | Command of option 23 | | |
| Byte28 | 0x00 | Command of option 24 | | |
| Byte29 | 0x00 | Command of option 25 | | |
| Byte30 | 0x00 | Command of option 26 | | |
| Byte31 | 0x00 | Command of option 27 | | |
| Byte32 | 0x00 | Command of option 28 | | |
| Byte33 | 0x00 | Command of option 29 | | |
| Byte34 | 0x00 | Command of option 30 | | |
| Byte35 | 0x00 | Command of option 31 | | Command word |
| Byte36 | 0x00 | Command of option 32 | | |
| Byte37 | 0x00 | Command of option 33 | | |
| Byte38 | 0x00 | Command of option 34 | | |
| Byte39 | 0x00 | Command of option 35 | | |
| Byte40 | 0x00 | Command of option 36 | | |
| Byte41 | 0x00 | Command of option 37 | | |
| Byte42 | 0x00 | Command of option 38 | | |
| Byte43 | 0xXX | XOR checkout | Check bit | |
| Byte44 | 0xF0 | Frame end | Frame end | |

6.2.2.2.1 Status page

Query command: 55 AA 07 00 00 80 00 00 00 00 87 F0.

Query response command contents of the status page are as shown in Table 6-22.

Table 6-22 Commands of status page

| Command word | Byte | Parameter description | Parameter type |
|--------------|------|-----------------------|----------------|
| Byte0 | 0x55 | Frame header byte 1 | Frame header |

| Command word | Byte | Parameter description | Parameter type |
|---------------|--------|-------------------------------------|---|
| Byte1 | 0xAA | Frame header byte 2 | |
| Byte2 | 0x13 | Length is 19 | Command length |
| Byte3 | 0x00 | Status page | Functional classification |
| Byte4 | 0x00 | Page 1 | Page number |
| Byte5 | 0x0A | TWIN612 Obervation type | ID number of module |
| | 0x0B | TWIN612 Thermography type | |
| | Others | Reserved | |
| Byte6 | 0x00 | | ID number of communication object |
| Byte7 | 0x0D | Year (13) | Program version |
| Byte8 | 0x06 | Month (06) | |
| Byte9 | 0x16 | Day (22) | |
| Byte10 | 0x1E | Focal spot temperature high 8 bit | Focal plane temperature (precision: 0.01) |
| Byte11 | 0x00 | Focal spot temperature low 8 bit | |
| Byte12 | 0x00 | Video system | Video system |
| Byte13 | 0x08 | 640×512 | ID number of resolution |
| | Others | Reserved | |
| Byte14 | xx | Machine identification code [31:24] | |
| Byte15 | xx | Machine identification code [23:16] | |
| Byte16 | xx | Machine identification code[15:8] | |
| Byte17 | xx | Machine identification code [7:0] | |
| Byte18~Byte21 | 0x00 | Reserved | |
| Byte22 | 0xFF | Checksum | Check bit |
| Byte23 | 0xF0 | Frame end | Frame end |

6. 2. 2. 2. 2 Setup page

Query command: 55 AA 07 01 00 80 00 00 00 86 F0.

Query response command contents of the setup page are as shown in Table 6-23.

Table 6-23 Commands of setup page

| Command word | Byte | Parameter description | Parameter type |
|----------------|------|--|---------------------------|
| Byte0 | 0x55 | Frame header byte 1 | Frame header |
| Byte1 | 0xAA | Frame header byte 2 | |
| Byte2 | 0x13 | Length is 19 | Command length |
| Byte3 | 0x01 | SETUP Status page | Functional classification |
| Byte4 | 0x00 | Page 1 | Page |
| Byte5 | xx | Automatic compensation time (xxmin) | Command of option 1 |
| Byte6 | 0x00 | Image not freezing | Command of option 2 |
| | 0x01 | Image freezing | |
| Byte7 | 0x00 | Real-time image | Command of option 3 |
| | 0x01 | Checker board pattern | |
| | 0x02 | Row gradients | |
| | 0x03 | Line gradients | |
| Byte8 | 0x00 | The rising of temperature calibration switch off | |
| | 0x01 | The rising of temperature calibration switch on | |
| Byte9 | 0x00 | Shutter control mode | Not supported |
| Byte10 | 0x00 | Shutter close off | |
| | 0x01 | Shutter close on | |
| Byte11 | 0x00 | Standard mode | Observation type |
| | 0x01 | Low noise mode | |
| Byte12~ Byte21 | 0x00 | Reserved | |
| Byte22 | 0xFF | Checksum | Check bit |
| Byte23 | 0xF0 | Frame end | Frame end |

6. 2. 2. 2. 3 Video page

Analog video page

Query response command contents of the analog video page are as shown in Table 6-24.

Table 6-24 Commands of analog video page

| Command word | Byte | Parameter description | Parameter type |
|---|------|--|---------------------------|
| Byte0 | 0x55 | Frame header byte 1 | Frame header |
| Byte1 | 0xAA | Frame header byte 2 | |
| Byte2 | 0x13 | Length is 19 | Command length |
| Byte3 | 0x02 | Video page | Functional classification |
| Byte4 | 0x00 | Analog video page (Page 1) | Page |
| Byte5 | 0x00 | Analog video off | |
| | 0x01 | Analog video on | |
| Byte6 | 0x00 | / | |
| | 0x01 | / | |
| | 0x02 | P-system 720x576 | |
| | 0x03 | N-system 720x480 | |
| Byte7 P-system 50/25/9 N-system 60/30/9 | 0x00 | 50/60Hz | |
| | 0x01 | 25/30Hz | |
| | 0x02 | 9Hz | |
| Byte8 | xx | Pseudo-color | |
| Byte9 | 0x00 | No | |
| | 0x01 | Mirror image in X direction | |
| | 0x02 | Mirror image in Y direction | |
| | 0x03 | Mirror images in X and Y directions | |
| Byte10 | xx | EZOOM zoom factor 8~64 | |
| Byte11 | xx | Coordinate X [15:0] of the center of zoomed area | |

| Command word | Byte | Parameter description | Parameter type |
|----------------|------|--|----------------|
| Byte12 | xx | Coordinate X [7:0] of the center of zoomed area | |
| Byte13 | xx | Coordinate Y [15:0] of the center of zoomed area | |
| Byte14 | xx | Coordinate Y [7:0] of the center of zoomed area | |
| Byte15 | 0x00 | Hot track switch | unsupported |
| Byte16~ Byte21 | 0x00 | Reserved | |
| Byte22 | 0xXX | Checksum | Check bit |
| Byte23 | 0xF0 | Frame end | Frame end |

Digital video page

Query command: 55 AA 07 02 01 80 00 00 00 00 84 F0.

Query response command contents of the digital video page are as shown in Table 6-25.

Table 6-25 Commands of digital video page

| Command word | Byte | Parameter description | Parameter type |
|--------------|------|---------------------------------------|---------------------------|
| Byte0 | 0x55 | Frame header byte 1 | Frame header |
| Byte1 | 0xAA | Frame header byte 2 | |
| Byte2 | 0x13 | Length is 19 | Command length |
| Byte3 | 0x02 | Video page | Functional classification |
| Byte4 | 0x01 | Digital video page (Page 2) | Page |
| Byte5 | 0x00 | External synchronization enabling off | |
| | 0x01 | External synchronization enabling on | |
| | 0x02 | External synchronization main mode | |
| Byte6 | 0x00 | Digital port parallel off | |
| | 0x01 | Digital port USB2.0 | |
| | 0x02 | Digital port CMOS | |
| Byte7 | 0x00 | YUV422 | Command of option 3 |

| Command word | Byte | Parameter description | Parameter type |
|----------------|------|-----------------------------|--------------------------------|
| | 0x01 | YUV422_ parameter line | Parallel output contents |
| | 0x02 | YUV16 | |
| | 0x03 | YUV16_ parameter line | |
| | 0x04 | Y16_YUV422 | |
| | 0x05 | Y16_ parameter line_ YUV422 | |
| Byte8 | 0x01 | CMOS8(MSB first) | Parallel output interface type |
| | 0x02 | CMOS8(LSB first) | |
| Byte9 | 0x00 | 50/60Hz | Command of option 5 |
| | 0x01 | 25/30Hz | |
| | 0x01 | Fall edge alignment | |
| Byte10~ Byte21 | 0x00 | Reserved | |
| Byte22 | 0xXX | Checksum | Check bit |
| Byte23 | 0xF0 | Frame end | Frame end |

Algorithm control page 1

Query command: 55 AA 07 02 04 80 00 00 00 00 81 F0.

Query response command contents of the algorithm control page 1 are as shown in Table 6-26.

Table 6-26 Algorithm control page 1

| Command word | Byte | Parameter description | Parameter type |
|--------------|------|-----------------------------|---------------------------|
| Byte0 | 0x55 | Frame header byte 1 | Frame header |
| Byte1 | 0xAA | Frame header byte 2 | |
| Byte2 | 0x13 | Length is 19 | Command length |
| Byte3 | 0x02 | Video page | Functional classification |
| Byte4 | 0x02 | Digital video page (Page 5) | Page |
| Byte5 | 0x00 | Ainti striation off | Option 1 command |
| | 0x01 | Ainti striation on | |
| Byte6 | XX | Brightness adjustment 0~16 | Option 2 command |
| Byte7 | 0x00 | Contrast adjustment:0~255 | Option 3 command |

| Command word | Byte | Parameter description | Parameter type |
|----------------|------|------------------------------|------------------|
| Byte8 | XX | Enhanced detail gain:0~255 | Option 4 command |
| Byte9 | 0x00 | EE enhancement algorithm off | Option 5 command |
| | 0x01 | EE enhancement algorithm on | |
| Byte10 | 0x00 | 2D noise reduction 0 | Option 6 command |
| | 0x01 | 2D noise reduction 1 | |
| | 0x02 | 2D noise reduction 2 | |
| Byte11 | | DRC mode 1 | DRC mode |
| | | DRC mode 2 | |
| Byte12~ Byte21 | 0x00 | Reserved | |
| Byte22 | 0xXX | Checksum | Check bit |
| Byte23 | 0xF0 | Frame end | Frame end |

6. 2. 2. 2. 4 Advanced application page

(1)Focusing page

Unavailable for the module.

(2)Defective pixel page

Query command: 55 AA 07 03 01 80 00 00 00 00 85 F0.

Query response command contents of the defective pixel page are as shown in Table 6-27.

Table 6-27 Commands of defective pixel page

| Command word | Byte | Parameter description | Parameter type |
|--------------|------|--|---------------------------|
| Byte0 | 0x55 | Frame header byte 1 | Frame header |
| Byte1 | 0xAA | Frame header byte 2 | |
| Byte2 | 0x13 | Length is 19 | Command length |
| Byte3 | 0x03 | Application | Functional classification |
| Byte4 | 0x01 | Defective pixel correction page (page 2) | Page |
| Byte5 | xx | Reserved | |

| Command word | Byte | Parameter description | Parameter type |
|----------------|------|---------------------------------|----------------|
| Byte6 | xx | Cursor location X[15:8] | |
| Byte7 | xx | Cursor location X[7:0] | |
| Byte8 | xx | Cursor location Y[15:8] | |
| Byte9 | xx | Cursor location Y[7:0] | |
| Byte10 | xx | AD value of cursor point [15:8] | |
| Byte11 | xx | AD value of cursor point [7:0] | |
| Byte12~ Byte19 | xx | Reserved | |
| Byte20 | xx | Cursor point Y16 [15:8] | |
| Byte21 | xx | Cursor point Y16 [7:0] | |
| Byte22 | 0xXX | Checksum | Check bit |
| Byte23 | 0xF0 | Frame end | Frame end |

(3) Menu function page

Unavailable for the module.

(4) Hot tracking page 1 (regional analysis)

Query command: 55 AA 07 03 04 80 00 00 00 00 80 F0.

Table 6-28 regional analysis page command

| Command word | Bytes | Parameter specification | Parameter type |
|--------------|-------|--|---------------------------|
| Byte0 | 0x55 | Frame header byte 1 | Frame header |
| Byte1 | 0xAA | Frame header byte 2 | |
| Byte2 | 0x28 | Length 40 | Command length |
| Byte3 | 0x03 | Application | Functional classification |
| Byte4 | 0x04 | regional analysis page (The fourth page) | Page number |
| Byte5 | 0x00 | Close analysis | Option 1 command |
| | 0x01 | Full screen analysis | |
| | 0x02 | Region 1 | Option 1 command |

| Command word | Bytes | Parameter specification | Parameter type |
|---------------|-------|---|---|
| | 0x03 | Region 2 | |
| | 0x04 | Region 3 | |
| Byte6 | xx | Upper left corner of regional Coordinate X[15: 8] | Option 2 command |
| Byte7 | xx | Upper left corner of regional Coordinate X[7:0] | |
| Byte8 | xx | Upper left corner of regional Coordinate Y[15: 8] | Option 3 command |
| Byte9 | xx | Upper left corner of regional Coordinate Y[7:0] | |
| Byte10 | xx | Upper left corner of regional Coordinate W[15: 8] | Option 4 command |
| Byte11 | xx | Upper left corner of regional Coordinate W[7:0] | |
| Byte12 | xx | Upper left corner of regional Coordinate H[15: 8] | Option 5 command |
| Byte13 | xx | Upper left corner of regional Coordinate H[7:0] | |
| Byte14~Byte20 | xx | Reserved | |
| Byte21 | xx | The coldest spot coordinate X[15: 8] | |
| Byte22 | xx | The coldest spot coordinate X[7:0] | |
| Byte23 | xx | The coldest spot coordinate Y[15: 8] | |
| Byte24 | xx | The coldest spot coordinate Y[7:0] | |
| Byte25 | xx | The coldest spot temperature/Y16[15: 8] | Observation type 0-65535, |
| Byte26 | xx | The coldest spot temperature/Y16[7:0] | Thermography type-50°C-1000°C, Magnify 10 times |
| Byte27 | xx | The hottest spot coordinate X[15: 8] | |
| Byte28 | xx | The hottest spot coordinate X[7:0] | |
| Byte29 | xx | The hottest spot coordinate Y[15: 8] | |
| Byte30 | xx | The hottest spot coordinate Y[7:0] | |

| Command word | Bytes | Parameter specification | Parameter type |
|--------------|-------|---|---|
| Byte31 | xx | The hottest spot temperature/Y16[15: 8] | Observation type 0-65535, Thermography type-50°C-1000°C, Magnify 10 times |
| Byte32 | xx | The hottest spot temperature/Y16[7:0] | |
| Byte33 | xx | Cursor spot coordinate X[15: 8] | |
| Byte34 | xx | Cursor spot coordinate X[7:0] | |
| Byte35 | xx | Cursor spot coordinate Y[15: 8] | |
| Byte36 | xx | Cursor spot coordinate Y[7:0] | |
| Byte37 | xx | Cursor spot temperature/Y16[15: 8] | Observation type 0-65535, Thermography type-50°C-1000°C, Magnify 10 times |
| Byte38 | xx | Cursor spot temperature/Y16[7:0] | |
| Byte39 | xx | Regional average temperature/Y16[15: 8] | Observation type 0-65535, Thermography type-50°C-1000°C, Magnify 10 times |
| Byte40 | xx | Regional average temperature/Y16[7:0] | |
| Byte41 | 0x00 | Reserved | |
| Byte42 | 0x00 | Reserved | |
| Byte43 | 0xXX | Checksum | Check bit |
| Byte44 | 0xF0 | Frame end | Frame end |

(5) Hotspot tracking page 3 (isotherm)

Query command: 55 AA 07 03 06 80 00 00 00 00 82 F0.

Table 6-29 Isotherm page command

| Command word | Bytes | Parameter specification | Parameter type |
|---------------|-------|---------------------------------------|---------------------------|
| Byte0 | 0x55 | Frame header byte 1 | Frame header |
| Byte1 | 0xAA | Frame header byte 2 | |
| Byte2 | 0x19 | Length 25 | Command length |
| Byte3 | 0x03 | Application | Functional classification |
| Byte4 | 0x06 | Hot tracking page (The sixth page) | Page number |
| Byte5~ Byte11 | 0x00 | Reserved | |
| Byte12 | 0x00 | Isotherm off | |

| Command word | Bytes | Parameter specification | Parameter type |
|-------------------|-------|---|--|
| | 0x01 | Isotherm on | |
| Byte13 | 0x00 | Upper and lower isotherm display mode | |
| | 0x01 | Medium isotherm display mode | |
| Byte14 | xx | Upper limit of isotherm threshold[15:8] | Observation type 0-65535, Thermography type-50°C -1000°C, Magnify 10 times |
| Byte15 | xx | Upper limit of isotherm threshold[7:0] | |
| Byte16 | xx | Lower limit of isotherm threshold[15:8] | |
| Byte17 | xx | Lower limit of isotherm threshold[7:0] | |
| Byte18~ Byte26 | 0x00 | Reserved | |
| Byte27 | 0x00 | White heat | |
| | 0x01 | fulgurite | |
| | 0x02 | iron red | |
| | 0x03 | hot iron | |
| | 0x04 | medical treatment | |
| | 0x05 | arctic | |
| | 0x06 | Rainbow 1 | |
| | 0x07 | Rainbow 2 | |
| | 0x08 | Trace red | |
| | 0x09 | Black heat | |
| Byte28 | 0xXX | Checksum | Check byte |
| Byte29 | 0xF0 | Frame end | Frame end |

6.2.2.2.5 Thermography page

(1) Parameter setting page

Query command: 55 AA 07 04 00 80 00 00 00 83 F0.

Query response command contents of the temperature measurement page are as shown in Table 6-30.

Table6-30 Thermography function page 1 command

| Command word | Byte | Parameter description | Parameter type |
|--------------|------|-----------------------|---------------------------|
| Byte0 | 0x55 | Frame header byte 1 | Frame header |
| Byte1 | 0xAA | Frame header byte 2 | |
| Byte2 | 0x19 | Length is 25 | Command length |
| Byte3 | 0x04 | Measurement page | Functional classification |

| Command word | Byte | Parameter description | Parameter type |
|--------------|-------|---|---|
| Byte4 | 0x00 | Page 1 | Page number |
| Byte5 | 0-255 | The value of distance setting | |
| Byte6 | 0-255 | The value of emissivity setting | |
| Byte7 | 00 | Minimum + maximum temperature of current analysis object | |
| Byte7 | 01 | Cross cursor spot+ maximum temperature | |
| | 02 | minimum + Cross cursor spot temperature | |
| Byte8 | 00 | Temperature unit: °C | |
| | 01 | Temperature unit: °F | |
| | 02 | Temperature unit: °K | |
| Byte9 | 0x00 | Reserved | |
| Byte10 | 0x00 | Reserved | |
| Byte11 | xx | Coordinate X [15:8] is based on byte7 value | The parameters(coordinate X, coordinate Y, temperature) of the first point are related to byte7 value: 00 means minimum temp. 01means cross cursor temp. 02 means Minimum temp. (actual temperature*10) |
| Byte12 | xx | Coordinate X [7:0] is based on byte7 value | |
| Byte13 | xx | Coordinate Y [15:8] is based on byte7 value | |
| Byte14 | xx | Coordinate Y [7:0] is based on byte7 value | |
| Byte15 | xx | The temperature[15 : 8] after calibration is based on byte7 value | |
| Byte16 | xx | The temperature[7 : 0] after calibration is based on byte7 value | |
| Byte17 | xx | Coordinate X [15:8] is based on byte7 value | |
| Byte18 | xx | Coordinate X [7:0] is based on byte7 value | |
| Byte19 | xx | Coordinate Y [15:8] is based on byte7 value | The parameters(coordinate X, coordinate Y, temperature) of the second point are related to byte7 value : 00: Maximum temp. 01: Maximum temp. 02: Cross cursor temp. |
| Byte20 | xx | Coordinate Y [7:0] is based on byte7 value | |
| Byte21 | xx | The temperature[15 : 8] after | |

| Command word | Byte | Parameter description | Parameter type |
|--------------|------|--|-------------------------|
| | | calibration is based on setting of byte7 value | (actual temperature*10) |
| Byte22 | xx | The temperature[7 :0] after calibration is based on setting of byte7 value | |
| Byte23 | xx | Reflected temp[15 : 8] | |
| Byte24 | xx | Reflected temp [7 : 0] | |
| Byte25 | xx | Humidity value | |
| Byte26 | xx | Temperature measurement range | |
| Byte27 | 0x00 | Reserved | |
| Byte28 | 0xXX | XOR checkout | Check bit |
| Byte29 | 0xF0 | Frame end | Frame end |

(2) Blackbody correction page

Query command: 55 AA 07 04 01 80 00 00 00 00 82 F0.

Query response command contents of the blackbody correction page are as shown in Table 6-31.

Table 6-31 Thermography function page 2 command

| Command word | Byte | Parameter description | Parameter type |
|----------------|------|---|---------------------------|
| Byte0 | 0x55 | Frame header byte 1 | Frame header |
| Byte1 | 0xAA | Frame header byte 2 | |
| Byte2 | 0x19 | Length is 25 | Command length |
| Byte3 | 0x04 | Measurement page | Functional classification |
| Byte4 | 0x01 | Page 2 | Page number |
| Byte5 | xx | Low blackbody temperature [15:8] | |
| Byte6 | xx | Low blackbody temperature [7:0] | |
| Byte7 | xx | High blackbody temperature [15:8] | |
| Byte8 | xx | High blackbody temperature [7:0] | |
| Byte9 | xx | Single point blackbody temperature [15:8] | |
| Byte10 | xx | Single point blackbody temperature [7:0] | |
| Byte11~ Byte27 | | Reserved | |
| Byte28 | 0xXX | XOR checkout | Check bit |
| Byte29 | 0xF0 | Frame end | Frame end |

Remark:

The "highest temperature", "lowest temperature", "central temperature" and "average temperature" mentioned in the above table are "10* actual temperature".

7 Mechanical interface specification

7.1 The structure of bare TWIN612 with 13mm lens

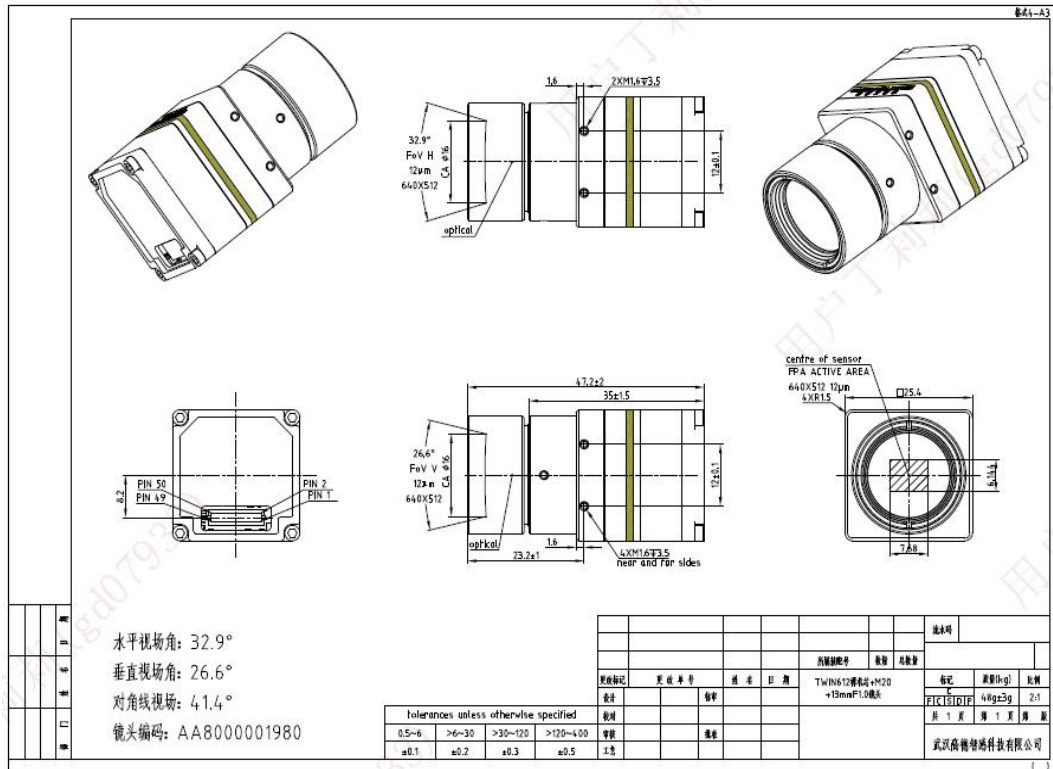


Fig. 7-1 TWIN612 module structure with 13mm lens

7.2 The structure of bare TWIN612 with 25mm lens

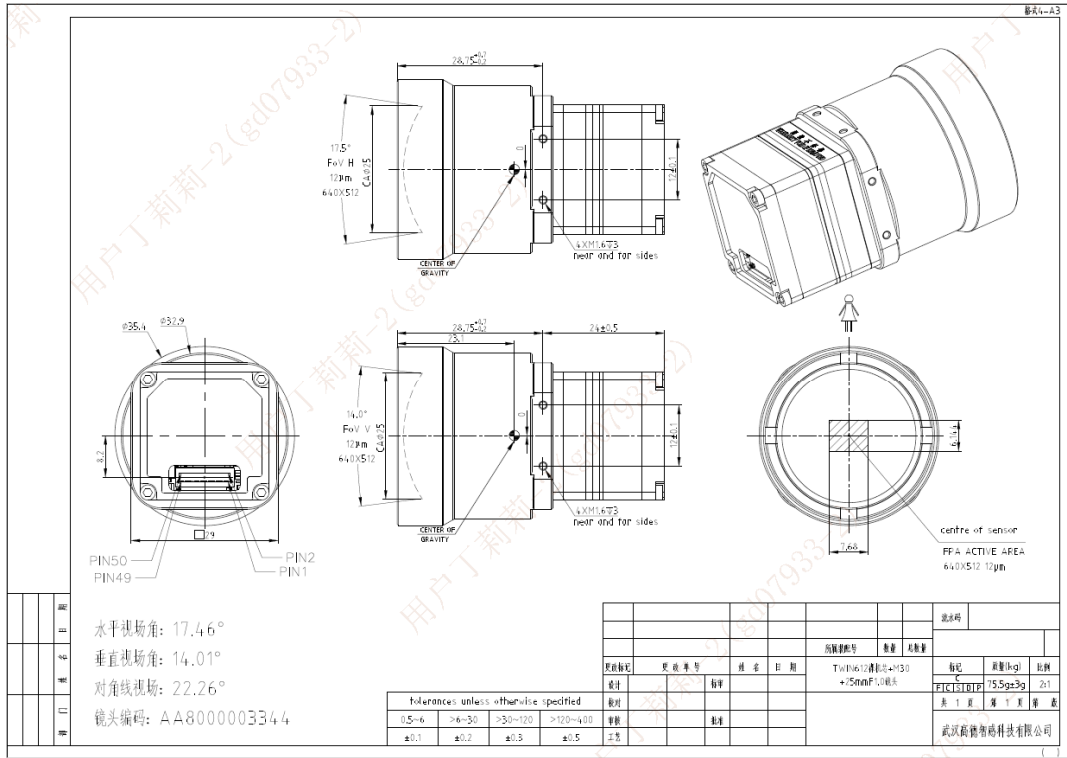


Fig. 7-2 TWIN612 module structure with 25mm lens

7.3 The structure of bare TWIN612 with 35mm lens

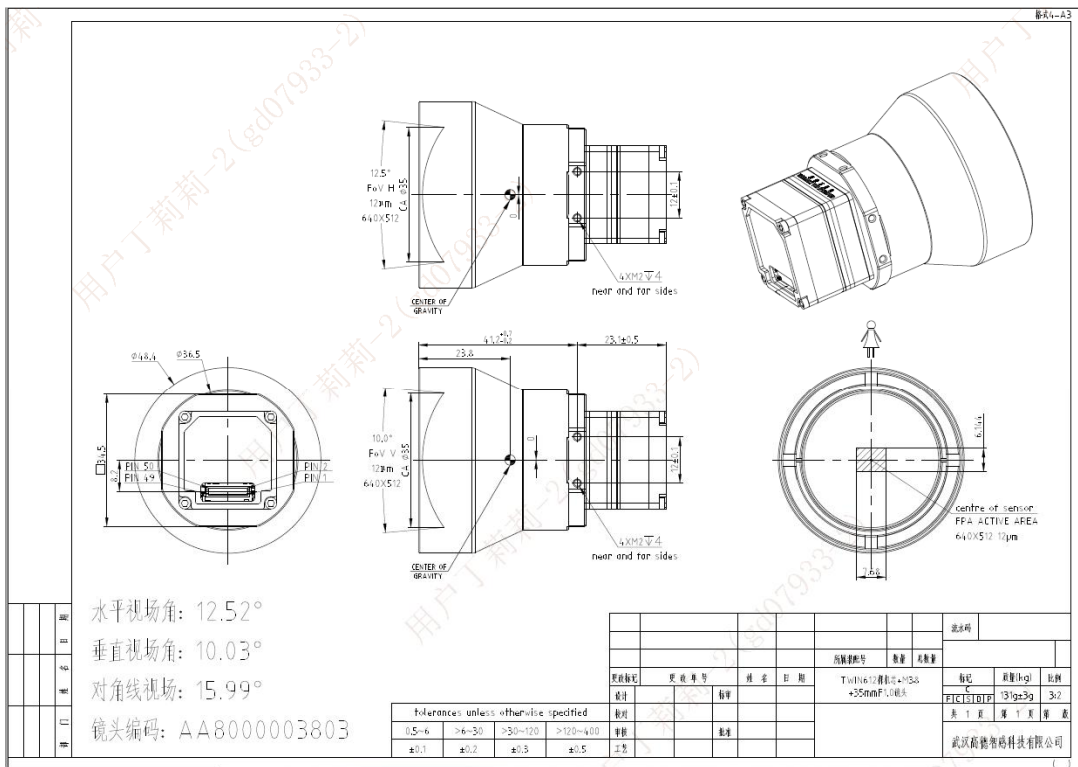


Fig. 7-3 TWIN612 module structure with 35mm lens

7.4 The structure of bare TWIN612 with 50mm lens

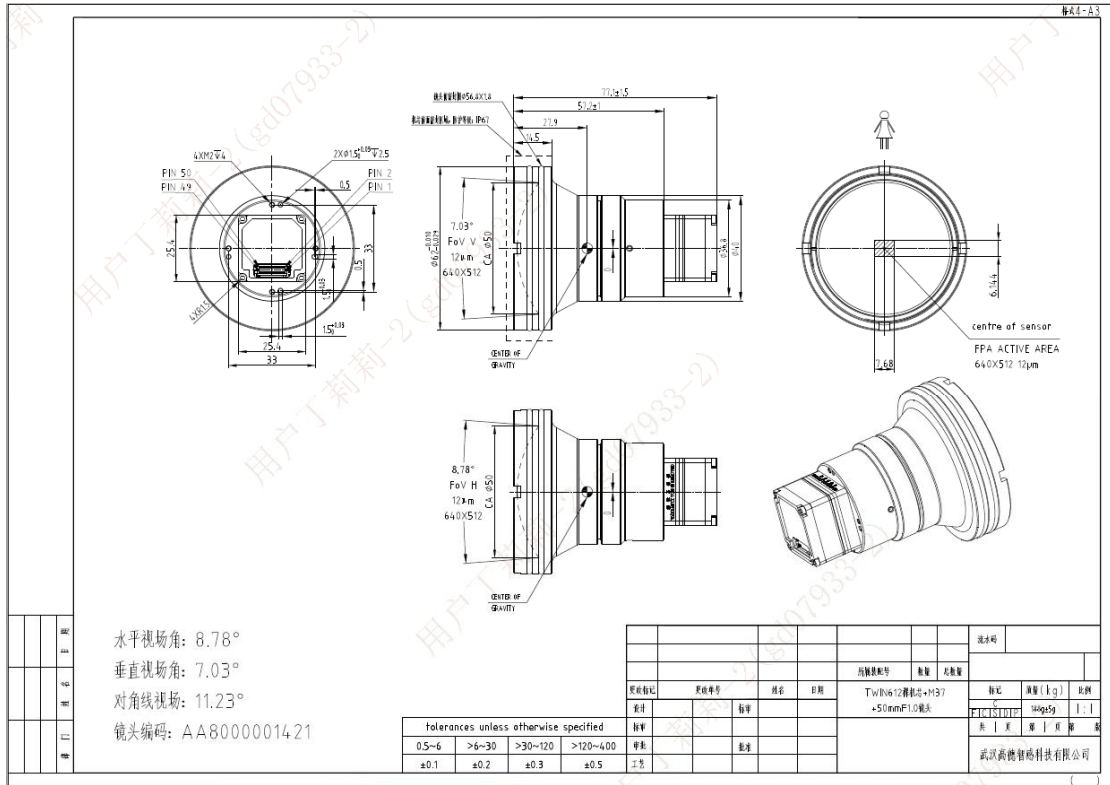


Fig. 7-4 TWIN612 module structure with 50mm lens

7.5 The structure of bare TWIN612 with 70mm lens

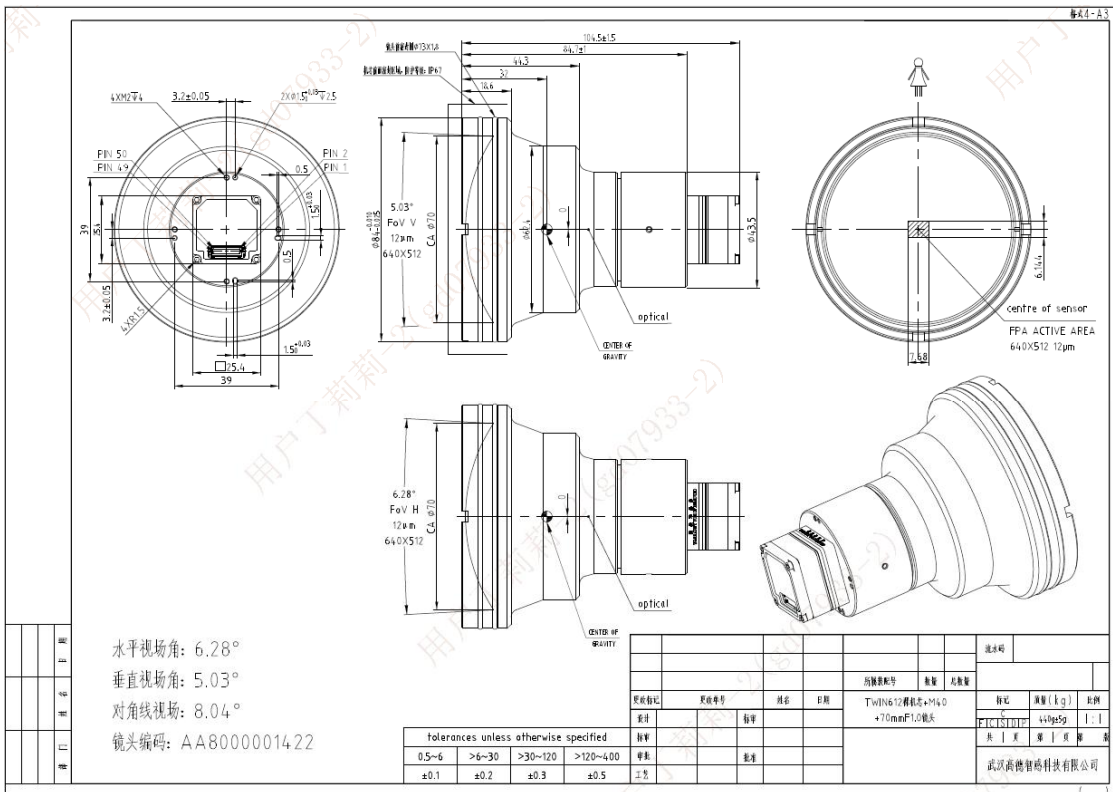


Fig. 7-5 TWIN612 module structure with 70mm lens